

Affiliated to

DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY UTTAR PRADESH, LUCKNOW



Evaluation Scheme & Syllabus

For

Bachelor of Technology

Electronics and Communication Engineering

Third Year

(Effective from the Session: 2024-25)

Bachelor of Technology

Electronics and Communication Engineering

EVALUATION SCHEME

SEMESTER-V

Sl. No.	Subject Codes	Subject Name	Type of Subject		erio	ods	I	Evaluati	ion Scheme	2	En Seme		Total	Credit
190.	Coues			L		P	СТ	ТА	TOTAL	PS	TE	PE		
WEEKS COMPULSORY INDUCTION PROGRAM														
1	AEC0501	Control System	Mandatory	3	1	0	30	20	50		100		150	4
2	AEC0502	CMOS Digital Integrated Circuit	Mandatory	3	0	0	30	20	50		100		150	3
3	AEC0503	Electromagnetic Field Theory and Antenna	Mandatory	3	1	0	30	20	50		100		150	4
4	ACSE0503	Design Thinking-II	Mandatory	2	1	0	30	20	50		100		150	3
5		Departmental Elective -I	Departmental Elective	3	0	0	30	20	50		100		150	3
6		Departmental Elective -II	Departmental Elective	3	0	0	30	20	50		100		150	3
7	AEC0551	Control System Lab	Mandatory	0	0	2				25		25	50	1
8	AEC0552	CMOS Digital Integrated Circuit Lab	Mandatory	0	0	2				25		25	50	1
9		Departmental Elective Lab	Mandatory	0	0	2				25		25	50	1
10	AEC0559	Internship Assessment –II	Mandatory	0	0	2				50			50	1
11	ANC0501/ ANC0502	Constitution of India, Law and Engineering / Essence of Indian Traditional Knowledge	Compulsory Audit	2	0	0	30	20	50		50		100	NA
12		*Massive Open Online Courses (For B.Tech. Hons. Degree)	*MOOCs											
		GRAND TOTAL											1100	24

* List of Recommended MOOCs (Massive Open Online Courses) for Third Year B. Tech Students (Semester-V)

S. No.	Subject Code	Course Name	University / Industry Partner Name	No of Hours	Credits
1	AMC0304	Wireless Evolution and 4G LTE Overview	Infosys Wingspan (Infosys Springboard)	52h 4m	4
2	AMC0305	C on Linux	Infosys Wingspan (Infosys Springboard)	10h 20m	0.5

PLEASE NOTE: -

- Internship (3-4 weeks) shall be conducted during summer break after semester-IV and will be assessed during Semester-V
- Compulsory Audit Courses (Non-Credit ANC0501/ANC0502)
 - > All Compulsory Audit Courses (a qualifying exam) has no credit.
 - > Total and obtained marks are not added in the Grand Total.

Abbreviation Used:

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., CE: Core Elective, OE: Open Elective, DE: Departmental Elective, PE: Practical End Semester Exam, CA: Compulsory Audit, MOOCs: Massive Open Online Courses.

List of Departmental	Electives
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Sl. No.	Subject Codes	Subject Name	Type of Subject	Bucket Name	Branch	Semester
1	AEC0511	Applied Industrial IoT	Departmental Elective-I		ECE	5
2	AEC0514	IoT Architecture and Protocols	Departmental Elective-II	Internet of Things	ECE	5
3	AEC0511P	Applied IoT Lab	Departmental Elective Lab	1111185	ECE	5
4	AEC0512	Embedded System Design	Departmental Elective-I		ECE	5
5	AEC0515	Introduction to Robotics and it's Applications	Departmental Elective-II	Embedded & Robotics	ECE	5
6	AEC0512P	Embedded System Design Lab	Departmental Elective Lab		ECE	5
7	AEC0513	Image Processing and Pattern Recognition	Departmental Elective-I		ECE	5
8	AEC0516	Machine Learning	Departmental Elective-II	Artificial Intelligence	ECE	5
9	AEC0513P	Image Processing and Pattern Recognition Lab	Departmental Elective Lab	80000	ECE	5

Bachelor of Technology

Electronics and Communication Engineering

EVALUATION SCHEME

SEMESTER-VI

SI. No	Subject	Subject Name	Type of	I	Period	s	I	Evaluat	ion Scheme	e	En Seme		Total	Credit
•	Codes		Subject	L	Т	P	СТ	ТА	TOTAL	PS	TE	PE		
1	AEC0601	Digital Signal Processing	Mandatory	3	1	0	30	20	50		100		150	4
2	AEC0602	Wireless Communication Networks	Mandatory	3	0	0	30	20	50		100		150	3
3	AEC0603	5G Technology	Mandatory	3	0	0	30	20	50		100		150	3
4		Departmental Elective-III	Departmental Elective	3	0	0	30	20	50		100		150	3
5		Departmental Elective-IV	Departmental Elective	3	0	0	30	20	50		100		150	3
6		Open Elective I	Open Elective	3	0	0	30	20	50		100		150	3
7	AEC0651	Digital Signal Processing Lab	Mandatory	0	0	2				25		25	50	1
8	AEC0652	Wireless Communication Lab	Mandatory	0	0	2				25		25	50	1
9		Departmental Elective Lab	Departmental Elective	0	0	2				25		25	50	1
10	AEC0659	Mini Project	Mandatory	0	0	2				50			50	1
11	ANC0602 / ANC0601	Essence of Indian Traditional Knowledge / Constitution of India, Law and Engineering	Compulsory Audit	2	0	0	30	20	50		50		100	NA
12		*Massive Open Online Courses (For B.Tech. Hons. Degree)	*MOOCs											
		GRAND TOTAL											1100	23

* List of Recommended MOOCs (Massive Open Online Courses) for Third Year B. Tech Students (Semester-VI)

S. No.	Subject Code	Course Name	University / Industry Partner Name	No of Hours	Credits
1	AMC0250	Data Structures and Algorithms	Infosys Wingspan (Infosys Springboard)	18h 5m	1
2	AMC0249	Wireless 5G Overview	Infosys Wingspan (Infosys Springboard)	55h 44m	4
3	AMC0282	Introduction to AI & ML	Infosys Wingspan (Infosys Springboard)	64h 13m	4

PLEASE NOTE: -

- Internship (3-4 weeks) shall be conducted during summer break after semester-VI and will be assessed during semester-VII
- Compulsory Audit Courses (Non-Credit ANC0601/ANC0602)
 - > All Compulsory Audit Courses (a qualifying exam) has no credit.
 - > Total and obtained marks are not added in the Grand Total.

Abbreviation Used:

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., CE: Core Elective, OE: Open Elective, DE: Departmental Elective, PE: Practical End Semester Exam, CA: Compulsory Audit, MOOCs: Massive Open Online Courses.

List of Departmental Electives

S. No.	Subject Codes	Subject Name	Type of Subject	Bucket Name	Branch	Semester
1	AEC0611	Privacy and Security in IoT	Departmental Elective-III		ECE	6
2	AEC0614	IoT Networks	Departmental Elective-IV	Internet of	ECE	6
3	AEC0614P	Advanced IoT and Mobile Applications Lab	Departmental Elective Lab	Things	ECE	6
4	AEC0612	Real Time Operating System	Departmental Elective-III		ECE	6
5	AEC0615	Robotics Design Mechanism	Departmental Elective-IV	Embedded & Robotics	ECE	6
6	AEC0615P	Robotics Lab	Departmental Elective Lab	Roboties	ECE	6
7	AEC0613	ANN & Deep Learning	Departmental Elective-III		ECE	6
8	AEC0616	Artificial Intelligence	Departmental Elective-IV	Artificial Intelligence	ECE	6
9	AEC0616P	AI & ML Lab	Departmental Elective Lab	Interngence	ECE	6

Bachelor of Technology Electronics and Communication Engineering

AICTE Guidelines in Model Curriculum:

A student will be eligible to get Under Graduate degree with Honors only, if he/she completes the additional MOOCs courses such as Coursera certifications, or any other online courses recommended by the Institute (Equivalent to 20 credits). During Complete B.Tech. Program Guidelines for credit calculations are as follows.

- 1. For 6 to 12 Hours =0.5 Credit
- 2. For 13 to18 =1 Credit
- 3. For 19 to 24 =1.5 Credit
- 4. For 25 to 30 =2 Credit
- 5. For 31 to 35 =2.5 Credit
- 6. For 36 to 41 =3 Credit
- 7. For 42 to 47 =3.5 Credit
- 8. For 48 and above =4 Credit

For registration to MOOCs Courses, the students shall follow Coursera registration details as per the assigned login and password by the Institute these courses may be cleared during the B. Tech degree program (as per the list provided). After successful completion of these MOOCs courses, the students shall provide their successful completion status/certificates to the Controller of Examination (COE) of the Institute through their coordinators/Mentors only. The students shall be awarded Honors Degree as per following criterion.

- i. If he / she secures 7.50 as above CGPA.
- ii. Passed each subject of that degree program in the single attempt without any grace.
- iii. Successful completion of MOOCs based 20 credits.

	Bachelor of Technology Third Year	
Course Code	AEC0501 LT	P Credits
Course Title	Control System 31	0 4
Course Objectives:	The student will learn about	
1	The basics of control systems along with different types of feedback and its effect. Introduction to block d techniques and signal flow graph	iagram reduction
2	Analysis of time domain response for various types of inputs along with the time domain specifications.	
3	Distinguish the concepts of absolute and relative stability for continuous data systems along with different analyse the system stability.	methods and
4	The concept the state space analysis of a control system.	
5	The digital control system and its analysis.	
	Course Contents / Syllabus	
UNIT-I	Introduction to Control Systems	8 hours
UNIT-II	Time Domain Analysis of Control Systems	8 hours
•	y state response, Input test signal, Time response of a first order control system, Time response of a sec Error, Sensitivity, Design of Control system: PD, PI, PID controller	ond order control
UNIT-III	Stability of Control Systems	8 hours
2	f characteristic equation, Routh Hurwitz criterion, Root-Locus Technique, Frequency domain analysis of iterion, stability analysis with the Bode plot, relative stability: gain margin and phase margin. Compe-	2
UNIT-IV	State Variable Analysis	8 hours
1 I	ntation, The concept of state, Block diagram for a state equation, Transfer function decomposition: Direction, Parallel decomposition, Solution of state equation, Transfer matrix, Controllability, and Observability.	
UNIT-V	Discrete Data Control System	8 hours
	orm and its relationship with Laplace-transform, transfer function of discrete data system, State equations omain properties of discrete data system, Stability of discrete data system, Steady state error analysis of di	
	At the end of this course students will demonstrate the ability to	

CO 1	Describe the basics of control systems along with different types of feedback and its effect.	K ₁ , K ₂			
CO 2	Interpret the time domain response analysis for various types of inputs along with the time domain specifications.	K ₃ , K ₄			
CO 3	CO 3 Distinguish the concepts of absolute and relative stability for continuous data systems along with K ₃ , different methods and analyse the system stability.				
CO 4	Analyse the nonlinear control system using the state space analysis.	K ₁ , K ₂			
CO 5	Identify the digital control system and its analysis using z-transform.	K ₁ , K ₃			
Text books		•			
1. I. J. Na	grath& M. Gopal, "Control System Engineering", 6th Ed. New Age International Publishers, 2018.				
2. B.C. K	uo& Farid Golnaraghi, "Automatic Control Systems", 9th Edition, John Wiley India, 2008.				
Reference Boo	ks				
1. Norma	n S. Nise, "Control Systems Engineering", 7 th Edition, John Wiley India.				
2. Richard	d C. Dorf, Robert H. Bishop, "Modern Control Systems", 13 th Edition, Pearson				
3. Karl J.	Åström, "Adaptive Control", Pearson Education India, 2006				
4. M. Goj	pal, "Digital control System, 6th Ed. New Age International Publishers				
NPTEL/ Yout	ube/ Faculty Video Link:				
Unit I	https://nptel.ac.in/courses/106/102/106102181/ https://nptel.ac.in/courses/117/105/117105080/ https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK				
Unit II	https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK				
Unit III	https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK				
Unit IV	https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK				
Unit V	https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK				

	Bachelor of Technology Third	I cai	
Course Code	AEC0502	LTP	Credits
Course Title	CMOS Digital Integrated Circuit	300	3
Course Objectives	: Students will learn about		
1	MOS and CMOS logic gate design.		
2	CMOS Combinational and Sequential logic circuit design		
3	Dynamic logic circuit Design		
4	VLSI design methodology		
5	Different ASIC Design Flow		
Pre-requisites: Bas	sic knowledge of MOSFET and Digital Electronics		
	Course Contents/Syllabus		
UNIT-I	MOSFET and CMOS Theory		8 hours
CMOS NAND, NO	OR, XOR and XNOR gates, Transistor sizing.	elays, noise margin, static &	
CMOS NAND, NO UNIT-II	•		8 hours
UNIT-II	DR, XOR and XNOR gates, Transistor sizing.	n	8 hours
UNIT-II CMOS Combinatio	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit desig	n lexers using CMOS.	
UNIT-II CMOS Combinatio CMOS Sequential l	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit designed onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultip	n lexers using CMOS.	
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit design onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiplogic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC.	n lexers using CMOS.	
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit designed and Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiple logic circuits: Design SR latch, Simpler Implementation of SR Latch	n lexers using CMOS.	
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit design onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiplogic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC.	n lexers using CMOS.	
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi ADC: Flash Type A UNIT-III	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit design onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiple logic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC. ADC, Dual Slope ADC, Successive approximation ADC.	n olexers using CMOS. n, JK flip flop, D flip flop using	g CMOS. 8 hours
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi ADC: Flash Type A UNIT-III Logic Gate design u	DR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit design onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiple logic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC. ADC, Dual Slope ADC, Successive approximation ADC. Dynamic logic circuit Design using pass transistor, different Combinational Circuit design using transistor	n olexers using CMOS. n, JK flip flop, D flip flop using ransmission gate and Pseudo N	g CMOS. 8 hours IMOS logic.
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi ADC: Flash Type A UNIT-III Logic Gate design u	OR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit desig onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultip logic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC. ADC, Dual Slope ADC, Successive approximation ADC. Dynamic logic circuit Design	n olexers using CMOS. n, JK flip flop, D flip flop using ransmission gate and Pseudo N	g CMOS. 8 hours IMOS logic.
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi ADC: Flash Type A UNIT-III Logic Gate design u Dynamic logic circ	DR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit design onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiple logic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC. ADC, Dual Slope ADC, Successive approximation ADC. Dynamic logic circuit Design using pass transistor, different Combinational Circuit design using transistor	n olexers using CMOS. n, JK flip flop, D flip flop using ransmission gate and Pseudo N	g CMOS. 8 hours IMOS logic.
UNIT-II CMOS Combinatio CMOS Sequential 1 DAC: weighted resi ADC: Flash Type A UNIT-III Logic Gate design u Dynamic logic circ clock distribution. UNIT IV VLSI design metho	DR, XOR and XNOR gates, Transistor sizing. CMOS Combinational and Sequential logic circuit desig onal Circuit: Design Half Adder, Full Adder, Multiplexers, Demultip logic circuits: Design SR latch, Simpler Implementation of SR Latch istor DAC, R-2R Ladder Type DAC. ADC, Dual Slope ADC, Successive approximation ADC. Dynamic logic circuit Design using pass transistor, different Combinational Circuit design using the transistor, different Combinational Circuit design using the transition of the principle, non-ideal effects, domino CMOS logic, hig VLSI Design Methodology odology, design Hierarchy, concept of regularity, modularity & log using PGA, design flow, Design quality Parameters, computed	n olexers using CMOS. h, JK flip flop, D flip flop using ransmission gate and Pseudo N h performance dynamic CMC	g CMOS. 8 hours IMOS logic. DS circuits, clocking issues, 8 hours Full Custom, Semi-Custom

Introduction of Application Specific Integrated Circuit (ASIC) Design Flow: An overview of Backend VLSI Design Flow – Libraries, Floorplanning, Placement, Routing, Verification, Testing. Specifications and Schematic cell Design, Spice simulation Analysis of analog and digital circuits, Circuit Extraction, Electrical rule check, Layout Vs. Schematic (LVS), Post-layout Simulation and Parasitic extraction, Design format, Timing analysis, Back notation and Post layout simulation, ASIC design implementation.

Course Outcomes: After completion of this course students will be able to

CO 2Design CMOS Combinational and Sequential logic circuit.CO 3Implement various logic gate using Dynamic logic Technique.	
CO 3Implement various logic gate using Dynamic logic Technique.	K1, K2, K3
	K1, K2, K3
CO 4Discuss the VLSI design methodology and its design flow.	K1, K2
CO 5 Describe ASIC Design Flow.	K1, K2, K3

Text Books:

1. Sung-Mo Kang & YosufLeblebici, "CMOS Digital Integrated Circuits: Analysis & Design", Mcgraw Hill, 4th Edition.

2. A.S. Sedra and K.C. Smith, "Microelectronic Circuits," Saunder's College11 Publishing, 4th edition.

Reference Books:

1. Introduction to VLSI, Eshraghian&Pucknell, Tata McGraw-Hill Publishing Company Ltd., New Delhi, 2007

2. W.Wolf, Modern VLSI Design: System on Chip, Third Edition, Pearson, 2002.

Unit 1	https://www.youtube.com/watch?v=MuBiC9yz2fc
Unit 2	https://nptel.ac.in/courses/108/106/108106158, https://www.youtube.com/watch?v=UuafwIJAKhY
Unit 3	https://www.youtube.com/watch?v=tRakiNOYBxI&t=19s
Unit 4	$\underline{https://www.youtube.com/watch?v=v2XywtRAHxM\&t=2s}, \ \underline{https://www.youtube.com/watch?v=N5vQIMyeA3M\&t=1s}, \ https:/$
Unit 5	https://nptel.ac.in/courses/117/101/117101058/

	Bachelor of Technology Third Year		
Course Code	AEC0503	L T P	Credits
Course Title	Electromagnetic Field Theory and Antenna	310	4
Course Objective	s: The student will learn about		
1	Different coordinate systems, vector calculus, and their application in electromagne	etic field theory.	
2	The concept of static Electric and Magnetic fields.		
3	Maxwell's equations for time-varying fields, wave propagation in a different me concepts of Electromagnetic radiation.	edium, Poynting's T	heorem and basi
4	Fundamental properties of Antenna.		
5	Practical Antennas and their applications.		
Pre-requisites: Ba	sic fundamentals of vectors algebra.		
Course Contents	Syllabus		Hours
UNIT-I	Coordinate Systems and Transformation		8 hours
	Electrostatic fields and Magnetostatic fields sity, Electric field due to charge distribution, Electric flux density, Gauss's Law- Max e, boundary conditions, Magnetostatic fields, Ampere's circuit law, Maxwell's equation, y conditions.		
UNIT-III	Electromagnetic waves		8 hours
	ns in final form, plane wave propagation in different medium: lossy dielectrics, loss olarization, Poynting's theorem, radiation from small current element, power density an		space and good
UNIT-IV	Antenna fundamental		8 hours
	c antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, D a apertures, Effective height, The radio communication link.	Directivity and Gain,	Directivity and
UNIT-V	Practical Antennas		8 hours
1	, Design and its Characteristic, Application of Loop Antennas. Horn Antennas, Helical ip Antenna, Parabolic Reflector Antennas, Feed Methods for Parabolic Reflectors.	Antennas, The Log-P	Periodic Antenna,

Course Outo	comes: After completion of this course students will be able to	
CO	Apply different coordinate systems and vector calculus to solve problems of electromagnetic fields.	K3, K4
CO	2 Explain and apply the concepts of static Electric and Magnetic fields.	K2, K3
CO	B Explain Maxwell's equations and their applications.	K2, K3
CO	Explain and calculate the fundamental properties of Antenna.	K2, K4
CO	5 Analyze practical Antennas with applications.	K2, K3
Text Books:		
1. MN	O Sadiku, "Elements of Electromagnetics', Oxford University Press, 2014.	
	n D Kraus, Ronald J Marhefka and Ahmad S. Khan, "Antennas and Wave Propagation", Fourth Edition, Tata McGra	w Hill, 2011.
J. C. I	A. Datains, Antenna Theory Analysis and Design, John Whey, 2010.	
Reference B	ooks:	
1. WI	Hayt and JA Buck, "Engineering Electromagnetics", McGraw-Hill Education, 2013.	
	R. Harish, M. Sachidananda, "Antennas and Wave Propagation", Oxford University Press, 2007.	
3. R.I	. Yadava, Electromagnetic Waves, Khanna Publishing House, Delhi, 2018.	
	Das, Sisir K. Das, "Microwave Engineering", Tata McGraw Hill, 2001.	
	utube/ Faculty Video Link:	
Unit 1	https://www.youtube.com/watch?v=3qd1JT7sRG8	
Unit 2	https://www.youtube.com/watch?v=F5KFYBdjzuE&list=PLVFqK_9GOGXnV8fwd2YmUURVmECpCIShv	
Unit 3	https://www.youtube.com/watch?v=7NZhmOIyYQM	
U nit 4	https://www.youtube.com/watch?v=h51mFbIgZRI&list=PLbRMhDVUMngfytbQXzasPMHuWst4E-Ly8&index	<u>x=2</u>
Unit 5	https://www.youtube.com/watch?v=wx_tIvaajAI&list=PL3UZlxOnyu9CRoBFsG5x-VqYeC69FmMZT	

	Bac	nelor of Technology Third Year	
Course Code	ACSE0503	L T P	Credits
Course Title	DESIGN THINKING II	210	3
Course Objec	tives:		I
	of this course is to upgrade Design Thinking -Life Problem by applying Design Thinking	skills by learning & applying advanced and contextual Desig to create an impact for all the stakeholders	n Thinking Tools. It aims
Pre-requisites	: Student must complete Design Thinking-I	course	
		Course Contents / Syllabus	
UNIT-I	Introduction		10 HOURS
Visualization a with Balancing	nd it's importance in design thinking, refle g Priorities (<i>in class activity</i>), DBS Singapo , understanding practical application of desi	her Purpose, <i>in-class activity for LDO & sharing insights</i> ections on wheel of life (<i>in-class activity for visualization &</i> ore and Bank of Americas' Keep the Change Campaign. Lit gn thinking tools and concepts, case study on McDonald's M	ter of Light & Arvind Ey
Working on 1-	hour Design problem, Applying RCA and Br	ainstorm on innovative solutions.	
Main project a	llocation and expectations from the project		
UNIT-II	Refinement and Prototyping		8 HOUR
<i>class activity fe</i> Prototyping (C flows, storyboa Napkin Pitch,	or 10-100-1000gm & QBL onvergence): Prototyping mindset, tools fourds, acting/role-playing etc, importance of g Usability, Minimum Viable Prototype, Cont	n, QBL, Design Tools for Convergence – SWOT Analysis f r prototyping – Sketching, paper models, pseudo-codes, phy garnering user feedback for revisiting Brainstormed ideas, necting Prototype with 3 Laws, A/B Testing, Learning Launco , Right, Value Proposition, Case study: Careerbuddy, You-	vsical mockups, Interactio

Learning Launch.

In-class activities on prototyping- paper-pen / physical prototype/ digital prototype of project's 1000gm idea

UNIT-III	Storytelling, Testing and Assessment	8 HOURS
	Elements of storytelling, Mapping personas with storytelling, Art of influencing, Elevator Pitch, Success	sful Campaigns of well-
known examp	eles, in-class activity on storytelling.	
0	sign with people, conducting usability test, testing as hypothesis, testing as empathy, observation and shado	0
	alidation workshops, user feedback, record results, enhance, retest, and refine design, Software validation t	cools, design parameters,
1	sting, Taguchi, defect classification, random sampling	
V	Presentation and assessing the impact of using design thinking	
UNIT-IV	Innovation, Quality and Leadership	6 HOURS
	Jeed & Importance, Principles of innovations, Asking the Right Questions for innovation, Rationale	
	Philosophies, Customer perception on quality, Kaizen, 6 Sigma. FinTech case study of Design Thinking appl.	
	ypes, qualities and traits of leaders and leadership styles, Leaders vs Manager, Personas of Leaders &	
	agers with 13 Musical Notes, Trait theory, LSM (Leadership Situational Model), Team Building Models: 7	luckman's and Belbin's.
	Spatial elements for innovation	
UNIT-V	Understanding Human Desirability	8 HOURS
Program need	led to achieve the comprehensive human goal: the five dimensions of human endeavour(ManaviyaVyavsth	a) are: Education- Right
	- Sanskar), Health – Self-regulation (SwasthyaSanyam), Justice – Preservation (Nyaya- Suraksha), Product	
	ange – Storage (Vinimya – Kosh), Darshan-Gyan-Charitra (Shifting the Thinking)	
	dness and mutual fulfilment among the four orders of nature recyclability and self-regulation in nature,	Thinking expansion for
Interconnecte		
	f-exploration (Johari's window), group behaviour, interpersonal behaviour and skills, Myers-Briggs per	rsonality types (MBTI),
harmony: Sel	f-exploration (Johari's window), group behaviour, interpersonal behaviour and skills, Myers-Briggs per o repair relationships.	rsonality types (MBTI),
harmony: Sel FIRO-B test t		rsonality types (MBTI),
harmony: Sel FIRO-B test t	o repair relationships.	rsonality types (MBTI), K2
harmony: Set FIRO-B test t Course outco CO 1	o repair relationships. ome: After completion of this course, students will be able to Learn sophisticated design tools to sharpen their problem-solving skills	K2
harmony: Set FIRO-B test t Course outco CO 1 CO 2	o repair relationships. ome: After completion of this course, students will be able to Learn sophisticated design tools to sharpen their problem-solving skills Generate innovate ideas using design thinking tools and converge to feasible idea for breakthrough solution	K2 on K3, K4
harmony: Set FIRO-B test t Course outco CO 1	o repair relationships. ome: After completion of this course, students will be able to Learn sophisticated design tools to sharpen their problem-solving skills	K2

CO 5	Understand the role of a human being in ensuring harmony in society and nature.	K2
Textbooks		
1. Arun J	ain, UnMukt : Science & Art of Design Thinking, 2020, Polaris	
	Ambrose and Paul Harris, Basics Design 08: Design Thinking, 2010, AVA Publishing SA	
3. R R G	ur, R Sangal, G P Bagaria, A Foundation Course in Human Values and Professional Ethics, First Edition, 2009, T	Excel Books: New
Delhi		
Reference Bo	bks	
	Liedta, Andrew King and Kevin Benett, Solving Problems with Design Thinking - Ten Stories of What Work	s, 2013, Columbia
	s School Publishing	
	Soryan, Universal Human Values and Professional Ethics, 2022, Katson Books	
	umar, 101 Design Methods: A Structured Approach for Driving Innovation in Your Organization, 2013, John W	iley and Sons Inc,
New Je	sey Martin, Design of Business: Why Design Thinking is the Next Competitive Advantage, 2009, Harvard Busin	and Drand Deston
4. Roger MA	2. Martin, Design of Business. Why Design Thinking is the Next Competitive Advantage, 2009, Harvard Busin	less riess, Dostoli
	own, Change by Design, 2009, Harper Collins	
	oni, Design your Thinking: The Mindsets, Toolsets and Skill Sets for Creative Problem-Solving, 2020, Penguin E	ooks
	Fube/ Web Link	
Unit I <u>https://</u>	www.youtube.com/watch?v=6_mHCOAAEI8	
https://nptel.ac	.in/courses/110106124	
https://designt	ninking.ideo.com/	
https://blog.ex	periencepoint.com/how-mcdonalds-evolved-with-design-thinking	
Unit II <u>https://</u>	www.coursera.org/lecture/uva-darden-design-thinking-innovation/the-ibm-story-iq0kE	
https://www.c	oursera.org/lecture/uva-darden-design-thinking-innovation/the-meyouhealth-story-part-i-what-is-W6tTs	
https://onlinec	purses.nptel.ac.in/noc19_mg60/preview_	
Unit III <u>https:</u>	//nptel.ac.in/courses/109/104/109104109/	
https://www.d	thinking.com/2021/07/01/how-to-use-storytelling-in-design-thinking/	

Unit IV https://www.worldofinsights.co/2020/10/infographic-8-design-thinking-skills-for-leadership-development/

Unit V https://www.youtube.com/watch?v=hFGVcx1Us5Y

	Bachelor of Technolo	ogy Thir	rd Year
Course Code		LTP	Credits
Course Title	Applied Industrial IoT	300	3
Course Objec	tives: Student will learn about		
1	The basic introduction and layered architecture of IIoT.		
2	The technology used in various types of sensors and measure	ement.	
3	Different functionalities required for edge computing and gat		
4	The architecture, big data architecture and data configure arc	hitecture).
5	The security threats and gaps and provide the security solution		
Pre-requisites	Knowledge of basic fundamentals of IoT.		
•	Course Contents	s / Syllał	Dus
UNIT-I	Introduction to Industrial IoT		8 hours
Architecture,			pries of IoT, Examples of IoT in Industry, Layers of IIoT itecture, Review of Components in various layers of IoT,
UNIT-II	Data Acquisition and Measurement		8 hours
Industrial Syst		, marred	ct Measurement, Derived Measurement, Measurement from 8 hours
Edge Computi Quality Contro	ing, Gateway Overview, Types and Features of Gateway, Che	oice of (Gateway, Configuring the Gateway, IoT Video Analytics and
UNIT-IV	Platform Architecture		8 hours
• 1	er Architecture, Data Architecture, Big Data Architecture and bes of Analytics.	Stream	Processing, Storage Devices, Storage Technologies, Analytics
UNIT-V	HoT Security		8 hours
IIoT Device S		m and	Cloud Security, Threat Modeling, Industrial Example – IoT
	orkplace Solution.		
	•		
Course Outco	omes: After completion of this course students will be able t	0	
Course Outco	Analyze the scope and impact of IoT in daily life, society and		K ₁ , K ₂
			K ₁ , K ₂
	Analyze the scope and impact of IoT in daily life, society and Industry and able to architect the layers of IIoT. Understand the different technologies in thermal, pressure, sh	d near,	K ₁ , K ₂ K ₁ , K ₂
CO 1	Analyze the scope and impact of IoT in daily life, society and Industry and able to architect the layers of IIoT.	d near,	

CO 3	Identify the various functionalities that are required in edge	K ₁ , K ₂	
	computing and gateway.		
CO 4	Explain platform architecture, big data architecture and to configure	K ₁ , K ₂	
	the data storage architecture.		
CO 5	Foresee possible security threats including gaps and identify its	K_1, K_2	
	solutions.		
Text books			
1. Guang Zho	ou, China, Industrial IoT Technologies and Applications, 2016, Kindle	Edition	
2. Timothy C	hou Precision - Principles, Practices and Solutions for the Internet of T	hings, 2016 PHI	
Reference Bo	oks		
1. Mahmood,	Marchenko, Wireless Networks and Industrial IoT: Applications, Chal	llenges and Enablers 1st ed. 2021 Edition, Kindle Edition	
2. Ismail But	un, Industrial IoT: Challenges, Design Principles, Applications, and Sec	curity, Kindle Edition	
NPTEL/ Yout	tube/ Faculty Video Link:		
Unit 1	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=51		
Unit 2	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=57&lesson=58		
Unit 3	https://www.youtube.com/watch?v=QnK0rf3y69s		
Unit 4	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=33&lesson=38	3	
Unit 5	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=89&lesson=91		

	Bachelor of Technology Third Year				
Course Code	AEC0512	LTP	Credits		
Course Title	le Embedded Systems Design 3 0 0				
Course Object	ives: Student will learn about				
1	Understand the basic introduction to embedded system design requirements.				
2	Learn the STM32F401 board & its interfacing.				
3	Understand the Architecture of ARM CORTEX-M4 processor.				
4	Learn the programming techniques of ARM processor.				
5	Understand the concept of embedded Linux and Linux kernel architecture.				
Pre-requisites:	Knowledge of Microprocessor and Microcontroller				
	Course Contents / Syllabus				
UNIT-I	Embedded System Concepts		8 hours		
	Embedded Systems: Definition of Embedded System, Embedded Systems Vs G				
•	ification, Major Application Areas, Purpose of Embedded Systems, Design Con	siderations of Embedded Syste			
UNIT-II	STM32F401 Board & Interfacing		8 hours		
	ucleo Board, Interfacing with Analog World, Output Devices, Sensors and Ac		ment LED and LCD		
	facing with Temperature Sensor and LDR Light Sensor, Speed Control of DC M	lotor.			
UNIT-III	The ARM CORTEX-M4 Processor		8 hours		
	Arm architectures and processors, Structure and purpose of specific registers in				
	upt Controller (NVIC), Wakeup Interrupt Controller (WIC), Memory Protection	n Unit (MPU), Bus Interconnec	t and Debug System		
and Low Power					
UNIT-IV	ARM CORTEX-M4 Programming		8 hours		
Introduction to Benefits and d importance.	Arm Cortex-M4 Programming, Compare the C and Assembly programming lar rawbacks of high-level and low-level programming, Introduction to the Mb	iguages, C as Implemented in A bed Platform and CMSIS, M	Assembly Language, bed platform and its		
UNIT-V	Embedded Linux & Drivers		8 hours		
•	bedded Linux, Embedded Linux versus Desktop Linux, Embedded Linux Districture, Linux Start-Up Sequence, GNU Cross-p\Platform Tool chain, Linux Seria		bedded Linux, Linux		
Course Outcor	mes: After completion of this course students will be able to				
CO 1	CO 1 Compute the design considerations of embedded systems.				
CO 2Apply the knowledge to learn STM32F401 for various application.K1, K3, K4					
CO 2	Apply the knowledge to learn 51101521401 for various application.		K_1, K_3, K_4		

CO 4	Implement the programming techniques for ARM processor.	K ₃ , K ₄	
CO 5	Evaluate the concept of embedded Linux and kernel architecture.	K ₂ , K ₄ , K ₅	
Text books			
1.ARM system	m developers guide, Andrew N Sloss, Dominic Symes and Chris Wright, Elsevier, Morgan Kaufman	n publishers, 2008.	
2. The Defini	tive Guide to the ARM Cortex-M3, by Joseph Yiu, 2nd Edition, Newnes, 2009		
3. Embedded	Linux System Design and Development, P.Raghavan, Amol Lad, Sriram		
Neelakandan	, 2006, Auerbach Publications.		
Reference B	ooks		
1. Shibu K V	, —Introduction to Embedded Systems, Tata McGraw Hill Education Private Limited, 2009.		
2. Embedded	Systems: Architecture, Programming and design, Raj Kamal, Second Edition, Tata McGraw Hill pu	ıblisher, 2010.	
3. David E. S	imon, "An Embedded Software Primer", Pearson Education.		
4. ARM Syst	em-on-Chip Architecture, Steve Furber, Second Edition, Pearson, 2015		
NPTEL Link	ζS		
Unit 1	https://www.youtube.com/watch?v=y9RAhEfLfJs		
Unit 2	https://www.youtube.com/watch?v=C04ZthY8Yqk		
Unit 3	https://nptel.ac.in/courses/106/105/106105193/		
Unit 4	https://www.youtube.com/watch?v=csttt3VHxf8		
Unit 5	https://www.youtube.com/watch?v=h-ZP98qhEM8		

	Bachelor of Technology Third Year		
Course Code		ГР	Credits
Course Title	Image Processing and Pattern Recognition30	0	3
Course Objective: T	The student will learn about	·	
1	Basics of digital image and various operations on it.		
2	Image enhancement techniques in different domains.		
3	The various noises in images and restoration methods.		
4	Skills to segment a digital image with different methods.		
5	The basics of colour image processing and various image compression	technic	jues.
Pre-requisites: Basic	c fundamental of mathematics and signal processing		
	Course Contents / Syllabus		Hours
UNIT-I	Introduction To Image Processing & Image Formation		8 Hours
Basic image file form	nats, Geometric and photometric models, Image Sensing and Acquisition, In	mage S	ampling and Quantization, Basic
-	n Pixels, Linear and Nonlinear Operations on digital images, Applications of	-	
UNIT-II	Image Enhancement		8 Hours
Spatial Domain: Ba	sic Gray Level Transformations, Histogram based Processing, Enhancem	ent usii	ng Arithmetic/Logic Operations,
Spatial Filtering, Smo	oothing and Sharpening by Spatial Filtering.		
Frequency Domain	: Filtering in the Frequency Domain, Image Smoothing and Image Sharpe	ening U	sing Frequency Domain Filters,
Selective Filtering.		_	
UNIT-III	Image Restoration		8 Hours
Image Degradation/H	Restoration process model, Noise Models, Restoration in the presence of	of noise	only-spatial filtering, Periodic
noise reduction by fro	equency domain filtering.		
UNIT-IV	Image Segmentation & Image/Object Features Extraction		8 Hours
Edge Linking and Bo	oundary Detection, Thresholding: Otsu and adaptive, Region-Based Segm	entatio	n, Segmentation: Morphological
Watershed, K-means	and Fuzzy C-means, Wavelet transform, Discrete wavelet transform, Ho	ugh tra	nsform, Textural features - grey
level co-occurrence	matrix; Moments; Connected component analysis; Convex hull; Dista	nce tra	nsform, medial axis transform,
skeletonization/thinn			
UNIT-V	Color Image Processing & Morphological Filtering Basics		8 Hours
Fundamentals of diff	Ferent colour models - RGB, CMY, HSI, YCbCr, Lab; False colour; Pseuc	lo colo	ur; Enhancement; Segmentation,
	Operators, Top Hat Filters.		
Course Outcomes: A	After completion of this course, students will be able to		
CO 1	Apply knowledge of mathematics for image understanding and analysi	.s.	K1, K3
CO 2	Analyse various image enhancement techniques in different domains.		K3, K4

CO 3	Recognize various noises in images and apply restoration methods. K3, K4				
CO 4	Apply different segmentation techniques on image.	К3			
CO 5	Perform different operations on colour images as well as different morphological filtering techniques on images to analyse them. K2, K3				
Text Books:	·				
3. Rafael C. Go	onzalez, Richard E. Woods, Digital Image Processing Pearson, Third Edition, 201	0.", Prentice Hall of India.			
4. Anil K. Jain,	, Fundamentals of Digital Image Processing Pearson, 2002.				
Reference Books:					
1. Milan Sonka 2001.	a, Vaclav Hlavav, Roger Boyle, —Image Processing, Analysis and Machine Vis	ion, 2nd ed., Thomson Learning,			
2. Rangaraj M.	Rangayyan, —Biomedical Image Analysis, CRC Press, 2005				
3. Pratt W.K, –	-Digital Image Processing, 3rd ed., John Wiley & Sons, 2007				
4. Digital Imag	e Processing, 3rd Edition, by Rafael C Gonzalez and Richard E Woods. Publisher	: Pearson Education			
NPTEL/ Youtube/	Faculty Video Link:				
Unit 1	https://youtu.be/T0bgf3V7u-E				
	https://youtu.be/bJjgyTQ-BT4				
Unit 2	https://youtu.be/M7JxDHUW5cc				
	https://youtu.be/JfrcMYBouJE				
Unit 3	https://youtu.be/MrNafUqh860				
	https://youtu.be/gLTlQPYY_pw				
Unit 4	https://youtu.be/j3_Ck5oP5oI				
	https://youtu.be/q1J0VAYFkHg				
Unit 5	https://youtu.be/kSzramCsHA4				
	https://youtu.be/nlwH07G9Efg				

	Bachelor of	f Technology Third Year	
Course Code	AEC0514	LTP	Credits
Course Title	IoT Architecture and Protocols	300	3
Course Objecti	ves: Student will learn about		
1	The architectural overview and IoT reference are	chitecture.	
2	The open source architecture and design principl	les.	
3	The various types of IoT connectivity protocols.		
4	Different types of IoT layered protocols.		
5	Differences between Web of things and Internet	of things.	
Pre-requisites:	Knowledge of basic fundamentals of IoT		
	Course	e Contents / Syllabus	
UNIT-I	Reference Architecture		8 hours
		• • •	needed capabilities, IoT Reference Architecture-
Introduction, Fu	inctional View, Information View, Deployment a	and Operational View, Othe	r Relevant architectural views. Real-World Design
	roduction, Technical Design constraints, Data rep	presentation and visualizatio	n, Interaction and remote control, Wireless Sensor
Network.			
UNIT-II	IoT Architecture		8 hours
-	, , , , , , , , , , , , , , , , , , ,	1 1	deployment models- IoTivity: An Open source IoT
	w- IoTivity stack architecture- Resource model and	nd Abstraction. LoRaWAN	architecture, Channel access mechanism specific to
NB-IoT.			
UNIT-III	IoT Connectivity Protocols		8 hours
		cols, LAN Protocols, Serial	Protocols, IoT transmission Protocols, Wired LAN
	res and security in Bluetooth		
UNIT-IV	IoT Layered Protocols		8 hours
			ocols, Issues with IoT Standardization, Unified Data
		ocol Modbus, KNX, archite	cture and Protocol stack used in Zig bee, Network
layer, APS layer			
UNIT-V	Web of Things		8 hours
0	6,	•	n for WoT, Platform Middleware for WoT, Unified
Multitier Woll A	Architecture, WoTPortals and Business Intelligenc	e.	
Course Outcon	nes: After completion of this course students wi	ll be able to	
CO 1	Explain the architectural overview and IoT refer	ence model.	K1, K2
CO 2	Demonstrate the IoT reference architecture.		

CO 3	Analyze the various types of IoT connectivity protocols.	K1
CO 4	Explain the different types of IoT layered protocols.	K1, K2
CO 5	Describe the differences between Web of things and Internet of Things.	K1, K2
Text books		
1. Honbo Z	hou, "The Internet of Things in the Cloud: A Middleware Perspective", CRC Press, 2012	
2. Dieter U	ckelmann, Mark Harrison, Michahelles, Florian (Eds), "Architecting the Internet of Things"	', Springer, 2011
3. David Ea Press, 20	asley and Jon Kleinberg, "Networks, Crowds, and Markets: Reasoning About a Highly Cor 10.	nnected World", Cambridge University
Reference Book	ΣS	
1. Vijay Ma	adisetti and ArshdeepBahga, "Internet of Things (A Hands-on-Approach)",1st Edition, VPT	Г, 2014.
2. Francis o 2013	laCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Everyth	ing", 1st Edition, Apress Publications,
3. Cuno P f	ister, Getting Started with the Internet of Things, O" Reilly Media, 2011, ISBN: 978-1	
NPTEL/ Youtu	be/ Faculty Video Link:	
Unit 1	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=53	
Unit 2	https://www.youtube.com/watch?v=FRxRT0DjE7A	
Unit 3	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=20	
Unit 4	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=19	
Unit 5	https://www.youtube.com/watch?v=R52OCMtFqNA	

	Bachelor of Technology Th	ird Year	
Course Code	AEC0515	LTP	Credits
Course Title	Introduction to Robotics & Its Applications	300	3
Course Object	tives: Student will learn about		
1	The concept of robotics.		
2	Mathematical relations for forward and inverse kinematic analys	sis.	
3	The various types of actuators and drive systems.		
4	Different types of sensors for a robot in a specific job task.		
5	The applications of robotics in industry.		
Pre-requisites	Engineering mechanics, Basic Electrical & Electronics, Sensor &	Instrumentation	
	Course Contents / Sylla	abus	
UNIT-I	Introduction		8 hours
Classification	of Robots, Advantages and Disadvantages of Robots, Robot Con	mponents, Robot Degrees of F	reedom, Robot Joints, Robot
	obot Reference Frames, Programming Modes, Robot Characteristic	cs, Robot Workspace, Robot La	
UNIT-II	Kinematics of Robots		8 hours
•	ysis - Introduction, Robots as Mechanisms, Conventions, Matr	1 0	
	of Transformations Forward and Inverse Kinematics of Robots, Fo	orward and Inverse Kinematics	
UNIT-III	Actuators and Drive Systems		8 hours
	Characteristics of Actuating Systems, Comparison of Actuating		
	pprocessor Control of Electric Motors, Pulse Width Modulation,	Direction Control of DC Mot	ors with an H-Bridge, Speed
Reduction			
UNIT-IV	Sensors		8 hours
Introduction, S	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit	•	s, Force and Pressure Sensors,
Introduction, S Torque Sensor		•	s, Force and Pressure Sensors,
Introduction, S Torque Sensor Sensors	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit rs, Micro-switches, Visible Light and Infrared Sensors, Touch an	•	s, Force and Pressure Sensors, Sensors, Range Finders, Sniff
Introduction, S Torque Sensor Sensors UNIT-V	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit rs, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications	nd Tactile Sensors, Proximity S	s, Force and Pressure Sensors, Sensors, Range Finders, Sniff 8 hours
Introduction, S Torque Sensor Sensors UNIT-V Robotics appli	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit rs, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications ications in Manufacturing-Material transfer and machine loading/	/unloading, Processing operation	s, Force and Pressure Sensors, Sensors, Range Finders, Sniff 8 hours
Introduction, S Torque Sensors UNIT-V Robotics appli Assembly oper	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit rs, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications	/unloading, Processing operation	s, Force and Pressure Sensors, Sensors, Range Finders, Sniff 8 hours
Introduction, S Torque Sensors UNIT-V Robotics appli Assembly oper	Sensor Characteristics, Sensor Utilization, Position Sensors, Velocit rs, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications ications in Manufacturing-Material transfer and machine loading/ rations, Inspection automation. Limitation of usage of robots in pro-	/unloading, Processing operation	s, Force and Pressure Sensors, Sensors, Range Finders, Sniff 8 hours

CO 3	Interpret the various types of actuators and drive systems.	K4, K6
CO 4	Explain the different type's sensor for a robot in a specific job task.	K4, K5
CO 5	Describe the applications of robotics in industry.	K1, K3
Text books	·	·
1. Saeed B	Niku, "Introduction to Robotics – Analysis, Systems and Application" : PHI 2006	
2. J.J. Crai	g, Robotics, Addison-Wesley, 1986.	
3. K.S Fu,	R.C. Gonzalez, C.S.G. Lee, Robotics, McGraw Hill, 1987.	
Reference Bool	άS	
1. An Intro	duction to Robot Technology, by CoifetChirroza, Kogan Page.	
2. Robotic	Engineering - An Integrated Approach: Richard D. Klafter Thomas A.	
3. Robotics	for Engineers, by Y. Koren, McGraw Hill.	
NPTEL/ Youtu	be/ Faculty Video Link:	
Unit 1	https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1Fkg	<u>gPhpH&index=2</u>
Unit 2	https://www.youtube.com/watch?v=XOg1KT6xD04&list=PLyqSpQzTE6M_XM9cvjLL0_Azt11	FkgPhpH&index=4
Unit 3	https://youtu.be/ksOgvhYdqX8	
Unit 4	https://youtu.be/Gc4BiUGiV-Q	
Unit 5	https://youtu.be/pSEjWxqE3R0	

	Bachelor of Technology Third Year		
Course Code	AEC0516 LT	(Credits
Course Title	Machine Learning 300		3
Course Objectives: Stu	dent will learn about		
1	The machine learning and basics of statistics and probability theory.		
2	Neurons, neural networks, and multilayer perceptron.		
3	Identification of the dimensionality of data and its reduction using variou probabilistic learning.	s mathematical co	oncepts as well as
4	Various search and optimization techniques to the raw data.		
5	Various learning techniques and approaches.		
Pre-requisites: Basics of	f mathematics and python programming		
	Course Contents / Syllabus		
UNIT-I	Introduction	8	Hours
	ar Algebra, Statistical Decision Theory – Regression & Classification,	sias – variance, l	Linear Regression,
Multivariate Regression. UNIT-II	Artificial Neural Network	8	Hours
Multivariate Regression. UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep	Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch and P ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amount of th	8 tts Neurons, The	Hours Perceptron, Linear
Multivariate Regression. UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep	Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch and P ession, Back propagation algorithm.	8 tts Neurons, The nining data, number	Hours Perceptron, Linear
Multivariate Regression. UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. Th UNIT-III Dimensionality Reduct analysis, locally linear er Models: Gaussian Matri algorithm, Extensions of	Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch and P ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amount of the network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis, Fact nbedding, ISOMAP ix Models, Nearest Neighbour methods. Support Vector Machine (SVM SVM.	8 tts Neurons, The hining data, number 8 or analysis, Indep : Optimal separat	Hours Perceptron, Linear er of hidden layers, Hours Dendent Component tion, Kernels, SVM
Multivariate Regression. UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. Th UNIT-III Dimensionality Reduct analysis, locally linear er Models: Gaussian Matri	Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch and P ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amount of the network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis, Fact nbedding, ISOMAP ix Models, Nearest Neighbour methods. Support Vector Machine (SVM)	8 tts Neurons, The hining data, number 8 or analysis, Indep : Optimal separat	Hours Perceptron, Linear er of hidden layers, Hours pendent Component
Multivariate Regression. UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. Th UNIT-III Dimensionality Reduct analysis, locally linear er Models: Gaussian Matri algorithm, Extensions of UNIT-IV Optimization and Sear climbing.	Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch and P ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amount of the network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis, Fact nbedding, ISOMAP ix Models, Nearest Neighbour methods. Support Vector Machine (SVM SVM.	8 tts Neurons, The hining data, number 8 or analysis, Indep 2 3 4 4 4 4 4 4 4 4 4 4 4 4 4	Hours Perceptron, Linear er of hidden layers, Hours bendent Component tion, Kernels, SVM Hours Greedy search, hill

Reinforcement Learning: State and action spaces, the reward function, Markov chain decision process, Uses of Reinforcement Learning.

Learning with tree: Decision Tree, Classification and regression tree, Random Forest.

Unsupervised Learning: The k-means algorithm, Vector quantization, The self-organization feature map, Simulated annealing.

Course Outcomes: After completion of this course, students will be able to CO 1 Describe the basic concepts of machine learning, statistics, and probability K1 theory. Define and describe the Neurons, neural networks, and multilayer CO 2 K3 perceptron. Identify the dimensionality of data and reduces it using various K3, K4 CO 3 mathematical concepts as well as describe the probabilistic learning. Describe and apply various search and optimization techniques to the raw CO 4 K5 data. Illustrate and apply various learning techniques. CO 5K2 **Text Books:** 1. Stephen Marsland, "Machine Learing- An Algorithm Perspective", CRC Press, 2nd edition. 2. EthemAlpaydin, —Introduction to Machine Learning (Adaptive Computation and Machine Learning), The MIT Press 2004. 3. SimanHaykin, "Neural Netowrks", Prentice Hall of India 4. D.E. Goldberg, "Genetic Algorithms: Search, Optimization and Machine Learning", Addison Wesley **Reference Books:** 1. Kumar Satish, "Neural Networks", Tata Mc Graw Hill 2. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", Wiley India. 3. Bishop, C., Pattern Recognition and Machine Learning. Berlin: Springer-Verlag. 4. An Introduction to Genetic Algorithms, Melanie Mitchell, MIT Press, 2000. NPTEL/ Youtube/ Faculty Video Link: https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC Unit 1 https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC Unit 2 Unit 3 https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC Unit 4

Unit 5	https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC
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	Bachelor of Technology Third Year		
Course Code		ТP	Credit
Course Title	Control System Lab 0	02	1
Course Objectives:	The student will learn about		
1.	Application of MATLAB in Control System.		
2.	Analysis and plotting various pole-zero configuration in s-plane using	g MAT	ГLAB.
3.	The basics concept of time domain analysis and steady state error.		
4.	The stability of a given transfer function using various methods such locus.	ch as	Bode plot, Nyquist plot and root
5.	The fundamental concept of steady state analysis and discrete control	system	m
	List of Experiments		
Sr. No.	Name of Experiment	(CO
1	Introduction to MATLAB and Control System Toolbox.		CO1
2	Plot the pole-zero configuration in s-plane for the given transfer function $H(s) = \frac{2s+1}{s^2+5s+5}$		CO1
3	Determine the transfer function for given closed loop system in block diagram representation. R(s) + + + + + + + + + + + + + + + + + + +	5	CO2
4	A unity feedback control system has forward path transfer function given below, determine time response for unit step input, rise tim maximum overshoot.		CO3

	$G(s) = \frac{s+2}{s(s+1)}$	
5	The open loop transfer function of unity feedback control system is given below find the position error coefficient, velocity error coefficient and acceleration error coefficient.	CO3
	$G(s) = \frac{10}{(s^2 + 6s + 10)}$	
_	Determine gain margin phase margin and closed loop stability by using Bode plot. Transfer function is given below	CO4
6	$G(s)H(s) = \frac{4}{s(0.5s+1)(0.08s+1)}$	
_	Draw the Nyquist plot for open loop transfer function given below and comment on its closed loop stability.	CO4
7	$G(s)H(s) = \frac{2.2}{s(s+1)(s^2+2s+2)}$	
8	Plot the root locus plot for the system when the open loop transfer function is given by	CO4
	$G(s) = \frac{K}{s(s+4)(s^2+4s+13)}$	
	Obtain the state model for the transfer function given below	CO5
9	$\frac{C(s)}{R(s)} = \frac{s+2}{(s+3)(s+1)}$	

	The forward-path transfer function of a unity-feedback discrete-data control system with sample-and-hold is	CO5
10	$G_{ho}G(z) = \frac{0.0952z}{(z-1)(z-0.905)}$	
	The sampling period is $T = 0.1$ s.	
	(a) Plot the plot of $G_{ho}G(z)$ and determine the stability of the closed-	
	loop system. (b) Apply the w-transformation to $G_{ho}G(z)$ and plot the Bode plot of	
	$G_{ho}G(w)$. Find the gain and phase margins of the system.	
Course Outcomes: After	r successful completion of this Lab students will be able to	Blooms Level
CO 1	Classify different tools in MATLAB.	K1, K2, K3
CO 2	Evaluate the poles and zeros on s-plane along with transfer function of	K2, K3, K4
	a given system.	
CO 3	Evaluate the various specifications of time domain response of a given	K1, K3, K4
	system.	
CO 4	Examine the stability of a given transfer function using various	K1, K2, K3
	methods such as Bode plot, Nyquist plot and root locus.	
CO 5	Examine the concept of state variable analysis and discrete control	K2, K3, K4
	system	

	Bachelor of 7	Fechnology Third Year	
Course Code	AEC0552	L T P	Credit
Course Title	CMOS Digital Integrated Circuit Lab	0 0 2	1
Course	Objectives: The student will learn	· · ·	
1.	VLSI EDA Tool.		
2.	Designing of various Logic gates.		
3.	Analyze CMOS Inverter and Voltage Follower.		
4.	Analysis and verification of CMOS Combinational Circuits		
5.	Analysis and verification of CMOS Sequential Circuits.		
	List	of Experiments	
Sr. No.	Name of Ex	speriment	СО
1	Introduction to VLSI Basic and EDA Tools such as Microwind and or Siemens.		CO1
2	To design a 2-input NAND logic gate using 0.18 µm technol		C01
3	To design a 2-input NAND logic gate using 0.18 µm technol		CO2
4	To design a 2-input NOR logic gate using 0.18 µm technologic		CO2
5	To design a NMOS source amplifier using 0.18 µm technol		CO2
6	To design a voltage follower using 0.18 µm technology and		CO2
7	To design a CMOS inverter using 0.18 µm technology and		CO3
8	To design and study the characteristic of CMOS XOR gate		CO4
9	To design and study the characteristic of CMOS D flipflop		CO3
10	To design and study the characteristic of CMOS T flipflop		CO5
	Outcome: After successful completion of this Lab studen	ts will be able to	Blooms Level
CO 1	Demonstrate VLSI EDA Tool.		K ₃
CO 2	Design various Logic gates.		$K_{3,} K_{4}$
CO 3	Analyze CMOS Inverter and Voltage Follower.		K ₃ , K ₄
CO 4	Analyze and verify CMOS Combinational Circuits.		K2
CO5	Analyze and verify CMOS Sequential Circuits.		K ₁ , K ₂ , K ₃

		Bachelor of Technolo		
			LTP	Credits
Course Title		11	0 0 2	1
Cou	rse Objec	tives: Student will learn about		
	1	The interfacing of Bluetooth with Arduino and publishing d	lata to the cloud.	
	2	The connection of Node MCU and Thing speak cloud.		
	3	The controlling of LED, Home appliances with Node MCU		
	4	The connection of temperature and humidity sensor with No	ode MCU and blink app.	
	5	The detection of virgular motion and observation of various	parameters of agricultural land.	
Pre-	requisites	: Basic Knowledge of computer		
		Course Contents / Syllab	us	CO
1	Tointerfa usingBlu	ceBluetoothwithArduinoandwriteaProgramto turnLEDON/O etooth.	FFwhenmessageisreceivedfromSmartPhone	CO1
2	To publis	shArduinodatatothecloud.		CO1
3	To Conn	ect Node MCU with wi-fi Hotspots and sending Data to Thin	g speak Server using Node MCU.	CO2, CO3
4	To Contr	ol the LED with Node MCU using Blink App.		CO3
5	To contro	ol home appliances using Node MCU using Blink App.		CO2
6	To contro	ol home appliances using Raspberry Pi 3 and MQTT.		CO2, CO5
7	To contro	ol the servo motor rotation using Node MCU and Blink App.		CO2, CO4
8	To read the temperature and humidity using DHT11using Node MCU and Blink App.		CO2, CO4 CO5	
9	To detect	To detect the virgular motion for home security system using Node MCU and Blink App.		CO2, CO5
10		tor soil moisture and water level of agricultural land using No		CO1, CO2
		mes: After completion of this course students will be able		
(CO 1	The interfacing of Bluetooth devices with Arduino and applications, publication of data on cloud.	its K1, K2	
(CO 2	Analyze Thing speak cloud and blink app.	К3	
	CO 3	Controlling the home appliances using Node MCU, Raspbe Pi and blink app.		
		Understand the function of DHT11 with Node MCU and bl app.		
(CO 5	Apply the IoT techniques for various practical applications.	К5	

		Bachelor of Technology Third Year	1
	rse Code	AEC0512P L T P	Credit
	rse Title	Embedded System Design Lab0 0 2	1
Cou	rse Objec	tives: Student will learn about	
	1	Writing different programs for Arm based microcontroller.	
	2	Freedom KL25Z board to build a system.	
	3	Arm-based embedded system, and program to satisfy given user specifications.	
	4	Commercial tools to develop Arm-based embedded systems.	
	5	Commercial API and tools to accelerate the development cycle of Arm-based embedded systems.	
re-	requisites	: Microcontrollers & Basics of Embedded system	
	1	Course Contents / Syllabus	CO
1		C program to examine the assembly language program output of the compiler and the map file output of the linker.	CO1
2		e Thumb code to multiply the two 32-bit in memory at addresses 0x1234_5678 and 0x7894_5612, storing the result s 0x2000_0010.	cO1
3		d compile assembly code and debug the program image on an mbed board (namely the Freedom KL25Z board) Keil MDK-ARM tool.	CO2, CO2
4	Write an	assembly code subroutine to approximate the square root of an argument using the bisection method.	CO3
5	Write a p	program to configure a General Purpose Input Output (GPIO) peripheral in a low-level (register-level) in practice.	CO2
6	1	brogram to implement an interrupt handler in a low-level. You are required to demonstrate the interrupt mechanism itches and LEDs on the board.	CO2, CO
7	Write a p of the au	program to generate audio waves using the analogoutput, and use two potentiometers to tune the volume and pitch dio.	CO2, CO4
8	Write a p of music	brogram to design an audio player using the timer, PWM, and interrupts. The audio player will play a simple piece using the speaker, and display the melody of the music to the LEDs. Two potentiometers are used to adjust the eed and the volume respectively.	
9	Write a p	rogram to generate various signals using DAC which can be viewed on an oscilloscope or heard through a speaker.	CO2, CO5
10	Write a linker.	C program and examine the assembly language program output of the compiler and the map file output of the	cO1, CO2
Cou	rse Outco	mes: After completion of this course students will be able to	
	CO 1	Write a program for Arm based microcontroller.	K1
	CO 2	Analyze Freedom KL25Z board to build a system.	K4
	CO 3	Build an Arm-based embedded system, and program to satisfy given user specifications.	К3
	CO 4	Use commercial tools to develop Arm-based embedded systems.	K3

K3

				B	achel	lor of	Tecl	hnolo	gy T	hird	Year							
Course Co	ode	AEC	0513P										L	ТP	Cr	redit		
Course Ti	tle	Imag	ge Proo	cessing	g and	l Patte	ern l	Recog	gnitio	on La	b		0	02			1	
	bjectives: The stu																	
1.	Basic skills for	-	-	-		-												
2.	Basic concept of		0			-			-	ques.								
3.	Basic concept of	of ima	ge segr	nentat	tion fo	or ima	age a	nalys	is.									
4.	Analyze the spa					0												
5.	The use of vari	ious er	hancer	nent a	and se	egmen	tatio	n tecł	nniqu	es for	deve	loping	g cor	npute	r visi	ion ap	plicat	ion.
	1							lxper										
Sr. No.						Name											•	C O
1	Write a program																	CO1
2	Write a program texture) of an I		g MAT	ΓLAB/	/Pyth	on to	extra	ict dif	fferen	it attri	butes	(i.e.,	Geo	metric	cal ar	nd		CO2
3	Write a program	ım usin	g MAT	ΓLAB/	/Pyth	on for	r Ima	ige No	egatio	on.								CO2
4	Write a program	Write a program using MATLAB/Python for Power Law Transformation.							CO2									
5	Write a program using MATLAB/Python for Histogram Mapping and Equalization.						CO2											
6	Write a program	Write a program using MATLAB/Python for Image Smoothening and Sharpening.CO					CO1											
7	Write a program Operators.	ım usin	g MAT	ΓLAB/	/Pyth	on for	r Edg	ge Det	tectio	on usii	ng So	bel, P	rewi	tt and	Rob	erts		CO1
8	Write a program	ım usin	g MAT	ΓLAB/	/Pyth	on for	r Moi	rphol	ogica	l Ope	ratio	ns on]	Bina	ry Ima	ages.			CO3
9	Write a program	ım usin	g MA7	ΓLAB/	/Pyth	on for	r Pseu	udo C	Colori	ng.				-				CO5
10	Write a program	ım usin	g MAT	ΓLAB/	/Pyth	on for	the	segm	entati	ion us	sing v	vatersl	ned t	ransfo	orm.			CO3
11	Write a program	um to e	iminat	e the h	high f	freque	ncy o	comp	onent	ts of a	n im	age.						CO5
12	Write a program using MATLAB/Python to extract the image features for image segmentation CO4 using DWT Computation. CO4																	
	utcomes: After s											able to	0					
CO 1	Implement ima	-		-	-				-]	K3, K4
CO 2	Analyze the po	ower of	variou	ıs ima	ige res	storati	ion a	nd co	ompre	ession	tech	niques	•]	K2, K3
CO 3	Learn basic ski	tills for	image	segme	entati	ion and	d im	age a	nalys	is.							I	K1, K2

CO 4	Analyze the spatial/ texture features of image.				
CO 5	Implement and evaluate different enhancement and segmentation techniques for developing	K3, K4			
	computer vision applications.				

Course code	ANC0501	LTP	Credits
Course title	Constitution of India, Law and Engineering	200	NC
Course Objec	tives: In this course, the student will:		
1	Learn the legacies of constitutional development of India and philosophy behind it.	in India and understand the most diversified legal document	K ₁ , K ₂
2	Aware of the theoretical and functional aspects of	f the Indian Parliamentary System.	\mathbf{K}_1
3	Understand the legal concepts and its implications	s for engineers.	K2
4	Learn the law of intellectual property rights.	Ť	\mathbf{K}_1
5	Learn the role of engineering in business organization	ations and e-governance.	K_1
Pre-requisites	s: Political science		
	Course	Contents / Syllabus	
UNIT-I	Introduction and Basic Information about Ind	ian Constitution	6 hours
Meaning of th	e constitution law and constitutionalism, Historica	l Background of the Constituent Assembly, Government of I	ndia Act of 1935
and Indian In	dependence Act of 1947, Enforcement of the Con	stitution, Indian Constitution and its Salient Features, The	Preamble of th
Constitution, I	Fundamental Rights, Fundamental Duties, Directiv	ve Principles of State Policy, Parliamentary System, Federal	System, Centre
State Relations	s, Amendment of the Constitutional Powers and Pre-	ocedure, The historical perspectives of the constitutional ame	ndments in India
Emergency Pr	ovisions: National Emergency, President Rule, Fi	nancial Emergency, and Local Self Government - Constitu	tional Scheme in
India.			
UNIT-II	Union Executive and State Executive		6 hours
Powers of Indi	an Parliament Functions of Rajya Sabha, Function	s of Lok Sabha, Powers and Functions of the President, Comp	parison of power
		ns of Vice-President, Powers and Functions of the Prime Min	
		s, Judicial Review, Public Interest Litigation, Judicial Activity	
-	· · · ·	s – Powers and Functions of the Governor, Powers and Funct	
		re, Functions of High Court and Subordinate Courts.	
			4 hours
UNIT-III	Introduction and Basic Information about Leg	al System:	4 nours

District Const	s taken from decisions of judges constitute binding legal rules. The Court System in India and Foreign C umer Forum, Tribunals, High Courts, Supreme Court). Arbitration: As an alternative to resolving disput	es in the normal courts,
UNIT-IV	e in dispute can agree that this will instead be referred to arbitration. Contract law, Tort, Law at workplace Intellectual Property Laws and Regulation to Information	4 hours
	operty Laws: Introduction, Legal Aspects of Patents, Filing of Patent Applications, Rights from Patents,	
	l its Ownership, Infringement of Copyright, Civil Remedies for Infringement, Regulation to Information	
	Act, 2005, Information Technology Act, 2000, Electronic Governance, Secure Electronic Records and Di	
	tificates, Cyber Regulations Appellate Tribunal, Offences, Limitations of the Information Technology Act.	
UNIT-V	Business Organizations and E-Governance:	4 hours
	Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of	
	Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up.	
	e and role of engineers in E-Governance, Need for reformed engineering serving at the Union and S	State level, Role of I.T.
	in Judiciary, Problem of Alienation and Secessionism in few states creating hurdles in Industrial developm	
Course outco	me: After completion of this course students will be able to	
CO 1	Identify and explore the basic features and modalities about Indian constitution.	K1
CO 2	Differentiate and relate the functioning of Indian parliamentary system at the center and state level.	K2, K3
CO 3	Differentiate different aspects of Indian Legal System and its related bodies.	K2
CO 4	Discover and apply different laws and regulations related to engineering practices.	K3
CO 5	Correlate role of engineers with different organizations and governance models	K4
Text books		
	mikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill.	
2. Brij K	ishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.	
3 Prabuc	Ih Ganguli: Gearing up for Patents: The Indian Scenario, Orient Longman.	
Reference Bo		
	adehra: Patents, Trademarks, Designs and Geological Indication Universal Law Publishing - LexisNexis.	
	tive programme study material Company Law, Module II, by ICSI (The Institute of Companies Secretaries	of India) (Only
	nt sections i.e., Study 1, 4 and <u>https://www.icsi.edu/media/webmodules/publications/Company%20Law.pd</u>	· · · ·
	ook on e-Governance Project Lifecycle, Department of Electronics & Information Technology,	
	/www.meity.gov.in/writereaddata/files/eGovernance_Project_Lifecycle_Participant_Handbook-5Day_Cou	
Links		

Unit 1	https://legalaffairs.nalsar.ac.in/students/student/course-details/1
Unit 2	https://www.youtube.com/watch?v=lZ2tvimrLRQ&t=281s
Unit 3	https://www.youtube.com/watch?v=H0_olSSX6D8&t=2s
Unit 4	https://www.youtube.com/watch?v=WvduZOWoft0
Unit 5	https://www.youtube.com/watch?v=7SmrFh88Cuk

B. TECH. THIRD YEAR						
Course code	ANC0502	L T P	Credits			
Course Title	ESSENCE OF INDIAN TRADITIONAL KNOWLEDGE	2 0 0	2			
literature, culture, Indi	This course aims to provide basic knowledge about different the an religion, philosophy, science, management, cultural heritage and puter Organization and Architecture					
Tre-requisites.com	Course Contents / Syllabus					
UNIT-I	SOCIETY STATE AND POLITY IN INDIA		8 Hours			
Kingship, Council of of the State, Society in	Evolutionary Theory, Force Theory, Mystical Theory Contract Theory Administration Political Ideals in Ancient India Condition Ancient India, Purusārtha, Varnāshrama System, Āshrama or the he representation of Women in Historical traditions, Challenges fac	ons' of the Welfare of S e Stages of Life, Marria	ocieties, The Seven Limbs			
UNIT-II	INDIAN LITERATURE, CULTURE, TRADITION, AN		8 Hours			

Evolution of script and languages in India: Harappan Script and Brahmi Script. The Vedas, the Upanishads, the Ramayana and the Mahabharata, Puranas, Buddhist And Jain Literature in Pali,Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sanskrit Authors, Telugu Literature, Kannada Literature,Malayalam Literature ,Sangama Literature Northern Indian Languages & Literature, Persian And Urdu ,Hindi Literature

UNIT-III

INDIAN RELIGION, PHILOSOPHY, AND PRACTICES

8 Hours

Pre-Vedic and Vedic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophical Doctrines, Other Heterodox Sects, Bhakti Movement, Sufi movement, Socio religious reform movement of 19th century, Modern religious practices.

UNIT-IV

SCIENCE, MANAGEMENT AND INDIAN KNOWLEDGE SYSTEM

8 Hours

Astronomy in India, Chemistry in India, Mathematics in India, Physics in India, Agriculture in India, Medicine in India, Metallurgy in India, Geography, Biology, Harappan Technologies, Water Management in India, Textile Technology in India ,Writing Technology in India Pyrotechnics in India Trade in Ancient India/,India's Dominance up to Pre-colonial Times.

UNIT-VCULTURAL HERITAGE AND PERFORMING ARTS8 Hours

Indian Architect, Engineering and Architecture in Ancient India, Sculptures, Pottery, Painting, Indian Handicraft, UNESCO'S List of World Heritage sites in India, Seals, coins, Puppetry, Dance, Music, Theatre, drama, Martial Arts Traditions, Fairs and Festivals, UNESCO'S List of Intangible Cultural Heritage, Calenders, Current developments in Arts and Cultural, Indian's Cultural Contribution to the World. Indian Cinema.

COURSE OUTCOMES: After completion of this course students will be able to

CO 1	Understand the basics of past Indian politics and state polity.	K2
CO 2	Understand the Vedas, Upanishads, languages & literature of Indian society.	K2
CO 3	Know the different religions and religious movements in India.	K4
CO 4	Identify and explore the basic knowledge about the ancient history of Indian agriculture, science & technology, and ayurveda.	K4
CO 5	Identify Indian dances, fairs & festivals, and cinema.	K1
Toxt Books		

Text Books:

1. Sivaramakrishna (Ed.), Cultural Heritage of India-Course Material, Bharatiya Vidya Bhavan, Mumbai, 5th Edition, 2014.

2. S. Baliyan, Indian Art and Culture, Oxford University Press, India

3. Nitin Singhania, Indian Art and Culture: for civil services and other competitive Examinations, 3rd Edition, Mc Graw Hill

Reference Books:				
1. Romila Thapar, Readings In Early Indian History Oxford University Press, India				
2. Basham, A.L., The Wonder that was India (34th impression), New Delhi, Rupa & co.				

Bachelor of Technology Third Year							
Course Code	AEC0601	LTP	Credits				
Course Title	Digital Signal Processing	3 1 0	4				
Course Object	tives: The students will learn about						
1	1 The concept of digital signal processing, DFT, FFT & filtering in the frequency domain.						
2	The designing of Digital IIR filter from analog filter using	g different mappi	ng techniques for processing of discrete time signals.				
3	The designing of digital finite impulse response filters us	ing various meth	ods (windows, sampling etc.) & effect of finite word length in				
	digital filter.						
4	The different types of IIR & FIR filter structures and their						
5	The concept of multirate digital signal processing for vari	ous practical app	lications.				
Pre-requisites	Basic knowledge of signal & system						
	Course Co.	ntents / Syllabus	5				
UNIT-I	DFT and FFT		8 hours				
Basics of signa	l processing, classification of signal processing, Application	ons of Digital Sig	nal Processing in real world.				
Frequency An	alysis of Discrete-Time Systems: Discrete Time Fourier	Transform (DTF	T), Discrete Fourier Transform (DFT), Properties of the DFT,				
1	f DFT with DTFT & Z- transform. Linear Filtering usingCi						
Fast Fourier 1	Fransform: Radix-2 DIT-FFT & DIF-FFT algorithm, inve	erse DFT using F	FT algorithm.				
UNIT-II	UNIT-II Design of IIR Digital Filters 8 hours						
	Introduction to Filters, Classification of filter, Characteristic of digital filters, Filter Design Specifications.						
	. 1		ransformation, All- Pole Analog Filters: Butterworth and				
•	Chebyshev, Analog frequency transformation, Design of Digital Butterworth, and Chebyshev Filters, digital frequency transformation.						
UNIT-III	Design of FIR Digital Filter		8 hours				

band effect		
UNIT-IV	Realization of Digital Systems	8 hours
	on- basic building blocks to represent a digital system, recursive and non-rec	survive systems, basic structures of a digital system: Canonical and
	nical structures. Realization: Direct form, Cascade, Parallel form realization, continued frac	tion expansion. Ladder structures
	Realization: Direct form, Cascade, FIR Linear Phase Realization.	uon expansion, Ladder structures.
UNIT-V	Multirate Digital Signal Processing (MDSP)	8 hours
Quadrature Adaptive	on, Decimation, Interpolation, Sampling rate conversion: Single and Multis e mirror filters, Advantages of MDSP. Filter: Introduction & Example of adaptive Filter, The window LMS Algor I Gradient Adaptive Lattice Method.	
	utcomes: After successful completion of the course students will be able Explain the concept of DFT & FFT and linear filtering using circular	to K1, K2, K3, K5
	and linear convolution.	
CO2	Design the digital IIR filters using various transformation techniques.	KI, K2, K4, K5
CO3	Design and analyse the FIR Filters and the effect of finite word length in digital filter.	K1, K2, K4, K5
CO4	Realize the digital system through different methods of realization structures and their utilities.	K1, K2, K4
CO5	Explain the concept of multirate digital signal processing, adaptive signal processing & basics of digital signal processor.	K1, K2, K3, K4
Textbooks		
	n G Prokias, Dimitris G Manolakis, "Digital signal processing Principles A	
	penheim & Schafer, "Discrete Time Signal Processing", Pearson education, nny R. Johnson, "Digital Signal Processing", 3 rd edition, PHI Learning pvtI	
Reference		Au., 2007
1. 5.5	alivahanan, "Digital signal processing", 6th edition, McGraw Hill Education	pyt ltd.
	un K. Rawat, "Digital Signal Processing", 1 st edition, Oxford University Pro	
3. S.K	K. Mitra, 'Digital Signal Processing-A Computer Based Approach, McGraw	Hill, 4th Edition.

NPTEL/	YouTube/ Faculty Video Link:
Unit 1	https://nptel.ac.in/courses/117105134/
	 <u>http://www.digimat.in/nptel/courses/video/117105134/L38.html</u>
Unit 2	• https://ocw.mit.edu/resources/res-6-008-digital-signal-processing-spring-2011/video-lectures/lecture-15-design-of-iir-digital-filters-
	<u>part-2/</u>
	• https://youtu.be/9WkvA7JT2dw
Unit 3	• <u>https://youtu.be/RJrEaTJuX_A</u>
	• https://youtu.be/5ka_14DkoYQ
Unit 4	• https://youtu.be/4Q-R1E5B40Q
	• https://youtu.be/9iE29uDpr0g
Unit 5	https://youtu.be/HVGW85eGPQQ
	• <u>https://youtu.be/XVMTpDK3UTk</u>

	Bachelor of Techno	ology Third Ye	ar
Course Code	AEC0602	LTP	Credits
Course Title	Wireless Communication Networks	300	3
Course Objectiv	ves: The student will be able to learn about		
1	The basics of networking and various layers of models		
2	The in-depth study and functions of layers.		
3	The functioning of wireless communication systems and standards.	the evolution of	of different wireless communication systems and
4	The cell architecture and advanced modulation used for	wireless comm	inication.
5	Multiple access techniques and design issues and securit	ty issues associa	ted with Ad-hoc wireless networks.
Pre-requisites: l	Basic knowledge of communication and computer.		
	Course Conten	ts / Syllabus	
UNIT-I	Basics of Computer Network, Physical layer and Dat	a Link Layer	8 hours
OSI Model, TCP	/IP reference model, Understanding of Delay, Loss and Th	roughput, Netw	orking Devices
	yer : guided transmission media, wireless transmission, the er- Design issues, error detection and correction, element C PPP		
UNIT-II	Network Layer, Transport Layer and Application La	ver	8hours
	Activors Layer, Transport Layer and Appreadon La	iyei	onours
Network Laver	-Virtual and Datagram networks, IP protocol and addres	sing in the Inte	ernet the network layer in the internet (IPv4 and IPv6)
-	IPs, Routing algorithms	in the me	
U	r -Multiplexing and Demultiplexing, UDP, Principles of re	liable data trans	sfer, TCP, Congestion control, SIP protocol.
Application La	yer- Web and HTTP, E-mail, DNS, Socket programm rview, dynamic web document and http. Application Layer	ing with TCP	and UDP. DNS, electronic mail, World Wide Web
UNI`T-III	Introduction to Wireless Communication	,	8hours
communication s	1G/2G/3G/4G Terminology. evolution of cellular systems Fading, Requirements and Targets for Long Termions from LTE to LTEA - Wireless Standards.		nts, goals, and vision of the next-generation wireless
UNIT-IV	Cell Architecture and Modulation Technique		8hours
Small cells: Past	t, present, and future trends of cellular networks coverage	ge and capacity	of smallcell networks Interference management, D2D
architecture Tow	ards IoT Spectrum sharing.		-
Multicarrier mod	lulation, OFDM, diversity multiplexing trade-off, OFDM station relays, spectrum sharing.	system, smart-a	ntenna: beam forming, cognitive radio, software-defined
,			01
UNIT-V	Multiple Access Techniques and Wireless Networks	and II-1-1	8hours
	multiple access schemes (FDMA TDMA, CDMA, SDMA rms, Variable subcarrier spacing, supported transmission n	•	contention-based multiple access schemes (ALOHA and

Design Challenges in Ad-hoc wireless networks, the concept of cross-layer design, security in wireless networks, energy-constrained networks, MANET and WSN.

Course Outcom	es: After completion of this course students will be able to	
CO 1	Analyze the requirements for a given organizational structure and select the most appropriate networking architecture and OSI Model.	K1, K4
CO 2	Analyze and design the topological and routing strategies for an IP based networking infrastructure and explain the working knowledge of computer applications and Network Security.	K4, K6
CO 3	Explain the functioning of wireless communication systems and the evolution of different wireless communication systems and standards.	K2
CO 4	Explain architecture and modulation technique used for wireless communication systems.	K2
CO 5	Analyze the multiple access techniques and evaluate the design challenges and security issues associated with Ad-hoc wireless networks.	K2 K5
Text Books:		
1. Compute	r Networks- A Top-Down approach, Behrouz Forouzan, McGraw Hill	
	paport, R. W. Heath Jr., R. C. Daniels, and J. M. Murdock, Millimeter Wave	e Wireless Communication., Pearson Education, 2015.
3. Andrea C	Goldsmith, "Wireless Communications", Cambridge University Press, 2005.	
Reference Book	s:	
1. Compute	r Networks (4th edition), Andrew Tanenbaum, Prentice Hall	
	Garg, "Wireless Communications and Networks", Morgan Kaufmann Publis	hers an Imprint of Elsevier, USA 2009 (Indian reprint)
3. Compute	r Networking and the Internet (5th edition), Fred Halsall, Addison Wesley.	
4. Compute	r Networking- A Top-Down approach, 5th edition, Kurose and Ross, Pearson	n.
NPTEL/ Youtul	be/ Faculty Video Link:	
Unit 1	https://nptel.ac.in/courses/106/105/106105183/ https://nptel.ac.in/courses/106/105/106105081/	
Unit 2	https://swayam.gov.in/nd1_noc20_cs23/preview https://nptel.ac.in/courses/106105031	
Unit 3	https://www.youtube.com/watch?v=f2wlHL1Sok8&list=PLuv3GM6-g	gsE3ypUYh43pPuZsXxJVG1e7F
Unit 4	https://www.youtube.com/watch?v=AKXFwwcww_E	
Unit 5	https://www.youtube.com/watch?v=ycaz99NogS4&list=PLJ5C_6qdA	vBHroAfekCO

	Bachelor of Technology Third Year		
Course Code	AEC0603	LTP	Credits
Course Title	5G Technology	300	3
Course Objectives	: The student will learn about		
1	The basics of 5G architecture and protocols.		
2	The propagation scenarios and channel modelling.		
3	The 5G techniques i.e. massive MIMO and mm wave.		
4	The mobility and handoff management in 5G.		
5	The network slicing, Network Function Virtualization		
Pre-requisites: Wi	reless Communication		
	Course Contents / Syllabus		
UNIT-I	Introduction to 5G Architecture and Protocols		8 hours
Systems. 5G Requi	Propagation Scenarios and Channel Modelling requirements, propagation scenarios and challenges in the 5G modelling, Chan rements, Key Capabilities of 5G versus 4G, 5G operating scenario, mm wave tech		
5G UNIT-III	Massive MIMO Techniques		8 hours
Massive MIMO pro Massive MIMO, be	pagation channel models, Channel Estimation in Massive MIMO, Massive MIM	IO with Imperfe	
UNIT-IV	Mobility and Handoff Management		8 hours
5G, 5G QoS Flow I	obility management in 5G, Handoff management in 5G, QoS improvement with Descriptions and Characteristics. of routing protocols, IPv6 addressing.	5G, QoS mech	anisms offered by
UNIT-V	Network Slicing and Function Virtualization		8 hours
slicing challenges f	Concept, architecture, the status of network slicing in 5G standards, network s or 5G Networks. S Virtualization (NFV): Functionality, architecture, advantages for 5G network.	slicing in core r	networks, network

Course Out	comes: After successful completion of the course, the student will be able to:	Bloom's Level
CO 1	Demonstrate Radio access network and protocol stack.	K ₃
CO 2	Analyze indoor and outdoor propagation models.	K4
CO 3	Apply massive MIMO technique in wireless communication.	K3
CO 4	Apply mobility management in heterogeneous and network-controlled handover.	K3
CO 5	Demonstrate the fundamentals of network slicing core networks.	K ₃
Text Books:		
1. Martin Sa Blackwell.	uter "From GSM to LTE-Advanced Pro and 5G: An Introduction to Mobile Networks and Mobile Bro	oadband", Wiley-
	ran, Jose. F. Monserrat, Patrick Marsch, "Fundamentals of 5G Mobile Networks", Cambridge Univer echnology, Applications, Byron Edde, Pearson Education, 2004.	sity Press. Radar
	s G.Kanatos, Konstantina S.Nikita, Panagiotis Mathiopoulos, "New Directions in Wireless Communicati i", CRC Press.	on Systems from
4. Saad Asif,	"5G Mobile Communications Concepts and Technologies", first edition, CRC Press.	
Reference B	ooks	
	Rodriguez, "Fundamentals of 5G Mobile Networks", John Wiley &Sons.WHHayt and JA Buc etic", 7th Edition TMH, 2013.	k, "Engineering
	S.Rappaport, Robert W.Heath, Robert C.Danials, James N.Murdock "Millimeter Wave Wireless C Communications.	ommunications",
NPTEL/ Yo	utube/ Faculty Video Link:	
Unit 1	https://www.youtube.com/watch?v=aYJncUscfmk	
Unit 2	https://www.youtube.com/watch?v=khsqASfv2T4&list=PLxJYaXA6j4AbpWZmDztACJNA5vA3rvfM	10&index=6
Unit 2 Unit 3	https://www.youtube.com/watch?v=khsqASfv2T4&list=PLxJYaXA6j4AbpWZmDztACJNA5vA3rvfM https://www.youtube.com/watch?v=am3Zs8QpLLY	10&index=6

Unit 5	https://www.youtube.com/watch?v=pUlfcGyFCFo

	Bachelor of Technology Third Year		
Course Code	AEC0611	L T P	Credits
Course Title	Privacy and Security in IoT	300	3
Course Objectives:	Student will learn about		
1	The security requirements in IoT Architecture.		I
2	The basic concepts of cloud security and services.		
3	The cryptographic primitives and its role in IoT.		
4	The privacy and trust models for IoT.		
5	The network security and its management.		
Pre-requisites: Basi	ic fundamental of microprocessor, microcontroller & Embedded System		
	Course Contents / Syllabus		
UNIT-I	Securing the Internet of Things		8 hours
	Cloud Security for IoT IoT, offerings related to IoT from cloud service providers, Cloud IoT securit rections in cloud enabled IoT computing	ity controls, An enterp	8 hours
architecture, new dr	rections in cloud enabled for computing		
UNIT-III	Cryptographic Fundamentals for IoT		8 hours
	tives and its role in IoT, Encryption and Decryption, Hashes, Digital Signatur adamentals, cryptographic controls built into IoT messaging and communication		
UNIT-IV	Privacy Preservation and Trust Models For IoT		8 hours
	ssemination – Lightweight and robust schemes for Privacy protection – Trus unauthorized access.	st and Trust models for	TIOT – self-organizing
UNIT-V	Network Security and Management		8 hours
	ography, Authentication, integrity, key distribution and certification, Access n many layers. Infrastructure for network management, The internet standard		

Course Outcomes:	After completion of this course students will be able to	
CO 1	Explain security requirements in IoT Architecture.	K1, K2
CO 2	Realize the basic concepts of cloud security for IoT.	K1, K3
CO 3	Explain the cryptographic primitives and its role in IoT.	K1, K2
CO 4	Implement the various trust models for IoT.	K1, K4
CO 5	Realize the various types of network security and its management.	K1, K3
Text books		
1. Practical Inte	rnet of Things Security (Kindle Edition) by Brian Russell, Drew Van Duren	
2. Cryptograph	y & Networks Security Stallings, William 3rd edition	
Reference Books		
1. Securing the	Internet of Things Elsevier	
2. William Stal	lings, "High-Speed Networks and Internets, Performance and Quality of Service", Pearson	n Education
NPTEL/ Youtube/	Faculty Video Link:	
Unit 1	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=89&lesson=92	
Unit 2	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=75&lesson=79	
Unit 3	https://www.youtube.com/watch?v=jSsehESW37c	
Unit 4	https://www.youtube.com/watch?v=sMquG8gxRh4	
Unit 5	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=41&lesson=42	

	Bachelor of Technology Third Year		
Course Code	AEC0612	LTP	Credits
Course Title	Real Time Operating System	300	3
Course Objectives:	Student will learn about		
1	Embedded OS internals.		
2	The basic concepts of Real Time Operating System.		
3	Concepts of Process and Task Scheduling.		
4	Strategies to interface memory and I/O with RTOS kernel.		
5	Architecture of CMSIS-RTOS & process of RTX task managemen	it.	
Pre-requisites: Basi	c fundamental of microprocessor, microcontroller & Embedded System		
	Course Contents / Syllabus		
UNIT-I	Embedded of Internals		8 hours
	rocess Management, File Management, Memory Management, I/O Ma		
	on, POSIX Threads Inter Process Communication - Semaphore, Pipes,	•	
Module Programmir USB, Block & Netw	ng Schedulers and types of scheduling. Interfacing: Serial, Parallel Interfacing: Serial, Parallel Interfacing.	errupt Handling Linux Device	e Drivers: Character
UNIT-II	Overview of RTOS		8 hour
OS overview: OS o	components, OS structure, Types of Operating Systems, Basics of RT	OS: Real-time concepts, Char	acteristics of RTOS
Architecture of RTC RTOS.	DS, Classification of RTOS: Hard Real time and Soft Real-time, Firm	real time system, Advantage	and disadvantage of
UNIT-III	Process and Scheduling		8 hour
	on, Memory lay out of an executing program, Process control block s, RTX and Linux Examples.	, Process creation, Process 7	Termination, Contex
	of scheduling of tasks, scheduling criteria, scheduling algorithms non- Time Scheduling and aperiodic Real time scheduling.	pre-emptive or pre-emptive. Q	Quantum size of task

UNIT-IV	Concurrency and Memory Management	8 hours
Concurrency: Con	ncurrency Scheduling, Multiprocessing environment, Read-write by multiple CPUs and consister	ncy problem, Solutions with
	Hardware Mutex, Software Mutex, Example: Dekker's algorithm, Semaphore, Deadlock, Bankers	
	ment: Processes Need Memory, Address Binding & its types, Memory Hierarchy, Virtual Mer	mory, Memory Partitioning,
Paging, Segmentat	ion with Paging, File System, File Structure, Directory Structure, Disk, Interrupt & DMA.	
UNIT-V	RTX	8 hours
RTX structure, R	TX files, RTX task and time management, Simple Time Management APIs, Task Priority S	Scheme in RTX, Inter-Task
Communication, E	vent, Interrupt, Mutex, Semaphore, Mailboxes and Messages in RTX, RTX control functions, Arc	hitecture of CMSIS-RTOS.
Course Outcomes	: After completion of this course students will be able to	
CO 1	Explain Arm processor architectures.	K1, K2
CO 2	Realize the basic concepts of RTOS.	K1, K4
CO 3	Apply the concepts of Process and Task Scheduling.	K3
CO 4	Implement strategies to interface memory and I/O with RTOS kernel.	K2
CO 5	Analyze the architecture of CMSIS-RTOS & process of RTX task management.	K2, K4
Text books		
1. Venkateswa	aranSreekrishnan," Essential Linux Device Drivers", Ist Kindle edition, Prentice Hall, 2008	
2. Jonathan W	V. Valvano, "Real-Time Operating Systems for ARM Cortex-M Microcontrollers" Jonathan Valva	no; 4 edition.
Reference Books		
1. Jerry Coope	erstein, "Writing Linux Device Drivers: A Guide with Exercises", J. Cooperstein publishers ,2009	
2. Qing Li and	d Carolyn Yao, "Real Time Concepts for Embedded Systems" – Qing Li, Elsevier ISBN:1578201	1241 CMP Books © 2000
NPTEL/ Youtube	/ Faculty Video Link:	
Unit 1	https://www.youtube.com/channel/UCiwfpGavlOTzATgDSZJ62vA	
Unit 2	https://www.youtube.com/channel/UCiwfpGavlOTzATgDSZJ62vA	
Unit 3	https://www.youtube.com/watch?v=Lwa7n0G5OHc	
Unit 4	https://www.youtube.com/watch?v=Qske3yZRW5I	
Unit 5	https://www.youtube.com/watch?v=Q4qu4ADTy9Q	

	Bachelor of Technology Third Year	
Course Code	AEC0613 L T P	Credits
Course Title	ANN & Deep learning 300	3
Course Object	tives: Student will learn about	
1	The basic principles and techniques of artificial neural network and deep learning.	
2	PCA, auto encoders, and other type of encoders.	
3	Choices and limitations of a model for a given setting.	
4	How to apply deep learning techniques to practical applications.	
5	RNN, GRU & LSTM and will also learn how to critically evaluate model performance and in	terpret results.
Pre-requisites Machine Learn	Working knowledge of Linear Algebra, Probability Theory. It would be beneficial if the paing.	rticipants have done a course of
UNIT-I	Introduction	8 Hours
Representation	History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, N Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural	Networks, Back propagation.
Representation UNIT-II Gradient Desc interpretations,	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural D Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en	Networks, Back propagation. 8 Hours Component Analysis and it
Representation UNIT-II Gradient Desc	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural D Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en	Networks, Back propagation. 8 Hours Component Analysis and it
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization:	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural I Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders.	Networks, Back propagation. 8 Hours Component Analysis and it coders, Denoising auto encoders 8 Hours 8 Hours
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization:	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural 1 Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Lay	Networks, Back propagation. 8 Hours Component Analysis and it coders, Denoising auto encoders 8 Hours 8 Hours
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization: weight initializ UNIT-IV	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural I Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Lay ation methods, Batch Normalization, Learning Vectorial Representations of Words.	Networks, Back propagation. 8 Hours Component Analysis and it coders, Denoising auto encoders 8 Hours erwise Pre-training, Softmaxlaye
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization: weight initializ UNIT-IV	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural I Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layation methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures	Networks, Back propagation. 8 Hours Component Analysis and incoders, Denoising auto encoder 8 Hours erwise Pre-training, Softmaxlayer
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization: weight initializ UNIT-IV Convolutional I UNIT-V	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural I Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Lay ation methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures Neural Networks, LeNet, AlexNet, ZF-Net, VGGNet, ResNet, DenseNet. RNN and LSTM models ral Networks, Back propagation through time (BPTT), Vanishing and Exploding Gradients, '	Networks, Back propagation. 8 Hours Component Analysis and it coders, Denoising auto encoder 8 Hours erwise Pre-training, Softmaxlaye 8 Hours 8 Hours 8 Hours 8 Hours 8 Hours 8 Hours
Representation UNIT-II Gradient Desc interpretations, Sparse auto enc UNIT-III Regularization: weight initializ UNIT-IV Convolutional I UNIT-V Recurrent Neur Encoder Decod	Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural I Optimization & Dimensionality Reduction cent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principa Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto en coders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Lay ation methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures Neural Networks, LeNet, AlexNet, ZF-Net, VGGNet, ResNet, DenseNet. RNN and LSTM models ral Networks, Back propagation through time (BPTT), Vanishing and Exploding Gradients, '	Networks, Back propagation. 8 Hours Component Analysis and it coders, Denoising auto encoders 8 Hours erwise Pre-training, Softmaxlaye 8 Hours 8 Hours 8 Hours 8 Hours 8 Hours 8 Hours 8 Hours

CO 2		
	Apply neural networks using various learning techniques and formulate the artificial neural network with different layers.	K3, K5
CO 3	Describe deep neural networks (DNN) using various learning techniques and formulate DNN with different layers.	K3, K4
CO 4	Apply different architectures of deep learning and summarize the difference between them.	K5
CO 5	Apply different deep learning techniques to practical applications and evaluate their performance.	K2, K5
Text Books:		
1. S. Rajs Hall of	ekaran& GA Vijayalakshmi Pai, "Neural Networks, Fuzzy Logic and Genetic Algorithm: Synthes India.	is and Applications", Prentice
2. Simanl	Haykin, "Neural Netowrks", Prentice Hall of India	
3. Ian Go	odfellow and YoshuaBengio and Aaron Courville, Deep learning, MIT Press, 2016	
4. Charu,	C. Agrawal, Neural Networks and Deep Learning, Kindle edition, 2018	
Reference Bo	oks:	
	· Satish, "Neural Networks", Tata Mc Graw Hill	
	ne Intelligence: Demystifying Machine Learning, Neural Networks and Deep Learning, Press, 2019	
3. Notion		
 3. Notion 4. Bishop 	Press, 2019	
 Notion Bishop 	Press, 2019 , Pattern Recognition and Machine Learning, Springer tube/ Faculty Video Link:	
 Notion Bishop NPTEL/ Yout 	Press, 2019 , Pattern Recognition and Machine Learning, Springer	
 Notion Bishop NPTEL/ Yout 	Press, 2019 , Pattern Recognition and Machine Learning, Springer tube/ Faculty Video Link: https://www.youtube.com/watch?v=OBFZPivcdqg	
 Notion Bishop NPTEL/ Yout Unit 1 	Press, 2019 Image: Press, 2019 , Pattern Recognition and Machine Learning, Springer tube/ Faculty Video Link: https://www.youtube.com/watch?v=OBFZPivcdqg https://www.youtube.com/watch?v=4TC5s_xNKSs	
 Notion Bishop NPTEL/ Yout Unit 1 Unit 2 	Press, 2019 Image: Press, 2019 , Pattern Recognition and Machine Learning, Springer tube/ Faculty Video Link: <td></td>	

	Bachelor of Technology Third Year		
Course Code	AEC0614	L T P	Credits
Course Title	IoT Networks	300	3
Course Objectives	s: Student will learn about		
1	The different types of networks and its requirement.		
2	The principles behind the Modern Network approaches such as SDN	NFV and IoT.	
3	The various components of IoT enabled things.		
4	The basic concept of virtual machines and functions.		
5	The various security requirements.		
Pre-requisites: Ba	asics of IoT and its Protocols		
	Course Contents / Syllabus		
UNIT-I	Modern Networking		8 hours
Cloud Computing,	Internet of Things - Types of Networks and Internet Traffic, Demand:	Big Data, Cloud Computin	ng and Mobile Traffic
Requirements: QoS	S and QoE Routing Congestion Control, SDN and NFV, Modern Networking	Elements	-
UNIT-II	Software Defined Networks		8 hours
		lane, Open Flow Logical N	
Network Requirem	Software Defined Networks nents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu		
Network Requirem	nents, The SDN Approach, SDN and NFV Related Standards, SDN Data P		
Network Requirem	nents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu		
Network Requirem Flow Protocol, SDI UNIT-III	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu IoT Components	ire	Network Device, Open 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work	ire	Network Device, Open 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu IoT Components	ire	Network Device, Open 8 hours
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Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization	ire d Forum Reference Model,	Network Device, Open 8 hours ITU-T IoT Reference 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M	Inents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architecture IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch	ire d Forum Reference Model,	Network Device, Open 8 hours ITU-T IoT Reference 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architecture IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch anagement and Orchestration, NFV Use Cases, SDN and NFV	ire d Forum Reference Model,	Network Device, Open 8 hours ITU-T IoT Reference 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V	Inents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architecture IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch anagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security	d Forum Reference Model, itecture, NFV Infrastructure	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem	Intervention Interventin Interventin I	d Forum Reference Model, itecture, NFV Infrastructur ty, The Patching Vulnerab	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem	Inents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architecture IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch anagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security	d Forum Reference Model, itecture, NFV Infrastructur ty, The Patching Vulnerab	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem Privacy Requireme	Intervention Interventin Interventin I	d Forum Reference Model, itecture, NFV Infrastructur ty, The Patching Vulnerab	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours 8 hours
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem Privacy Requireme Course Outcomes	In the SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architecture IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Worl System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch anagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security ents, SDN Security, NFV Security, ETSI Security Perspective, IoT Securi ents Defined by ITU-T, An IoT Security Framework, The Impact of the New : After completion of this course students will be able to	d Forum Reference Model, itecture, NFV Infrastructur ty, The Patching Vulnerab	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours ility, IoT Security and
Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem Privacy Requireme	hents, The SDN Approach, SDN and NFV Related Standards, SDN Data P N Control Plane Architecture, REST API, SDN Application Plane Architectu IoT Components e of the Internet of Things, Components of IoT-Enabled Things, IoT Work System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Reference Arch anagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security ents, SDN Security, NFV Security, ETSI Security Perspective, IoT Securi ents Defined by ITU-T, An IoT Security Framework, The Impact of the New	d Forum Reference Model, itecture, NFV Infrastructur ty, The Patching Vulnerab	Network Device, Open 8 hours ITU-T IoT Reference 8 hours e, Virtualized Network 8 hours 8 hours

CO 3	Describe the various components of IoT Enabled Things.	K1, K3
CO 4	Explain the concept of virtual machines and their network functions.	K1, K3
CO 5	Describe the various requirements of security.	K2, K3
Text books		
1. "Foundations of	of Modern Networking: SDN, NFV, QoE, IoT, and Cloud" William Stallings Publisher: Addisor	n-Wesley 2015
2. SDN and NF Edition by Jim	Simplified: A Visual Guide to Understanding Software Defined Networks and Network Doherty	Function Virtualization 1st
Reference Books		
1. Software Defin	ned Networks: A Comprehensive Approach, Ist Edition by Paul Goransson Chuck Black	
2. Network Func	ion virtualization with a touch of SDN by Paresh Shah, Syed Farrukh Hassan, Rajendra Chayap	athi
NPTEL/ Youtube/ Fa	aculty Video Link:	
Unit 1	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=16	
Unit 2	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=75&lesson=76	
Unit 3	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=53	
Unit 4	https://www.youtube.com/watch?v=V15UJUR1uV4	
Unit 5	https://www.business.att.com/learn/tech-advice/the-security-benefits-of-software-defined-r	networkingsdnhtml

	Bachelor of Technology Third Year		
Course Code	AEC0615	L T P	Credits
Course Title	Robotics Design Mechanism	300	3
Course Objectives:	: Student will learn about		
1	Industrial robots and their operational workspace characteristics & the	he tools taking part in the ma	nufacturing process.
2	Dynamic analysis of drives.		
3	The feedback sensors its types & transporting devices.		
4	The feeding materials used according to application & orientation.		
5	Functional systems & prototypes of robots.		
Pre-requisites: Intr	roduction to Robotics & its Applications		
	Course Contents / Syllabus		
UNIT-I	Introduction		8 hours
Representatives of t	itions: Robots & its Kinds, Definition of Levels, Manipulators, Structure the Robot Family, Relationship between the Level of Robot "Intelligence" an vouts : Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping	nd the Product.	
Representatives of the Concepts and Lay	the Robot Family, Relationship between the Level of Robot "Intelligence" at outs : Processing Layout, Concept of an Automatic Manufacturing Proce	nd the Product.	
Representatives of t Concepts and Lay Kinematic Layout, H UNIT-II Electromagnetic Dri Kinematics and Co	the Robot Family, Relationship between the Level of Robot "Intelligence" arouts: Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping	nd the Product. ess, Productivity of a Manut Variable Moment of Inertia ontroller, Amplifiers, Dynam	facturing Process, The 8 hours
Representatives of t Concepts and Lay Kinematic Layout, H UNIT-II Electromagnetic Dri Kinematics and Co	the Robot Family, Relationship between the Level of Robot "Intelligence" at routs : Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping Dynamic Analysis of Drives ive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a V ontrol of Automatic Machines : Position Function, Camshafts, Master Co	nd the Product. ess, Productivity of a Manut Variable Moment of Inertia ontroller, Amplifiers, Dynam	facturing Process, The 8 hours
Representatives of t Concepts and Lay Kinematic Layout, H UNIT-II Electromagnetic Dri Kinematics and Co of Harmful Vibratio UNIT-III Linear and Angular	 the Robot Family, Relationship between the Level of Robot "Intelligence" are vouts: Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping Dynamic Analysis of Drives ive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Vontrol of Automatic Machines: Position Function, Camshafts, Master Coons, Automatic Vibration Damping, Electrically Controlled Vibration Damp 	nd the Product. ess, Productivity of a Manuf Variable Moment of Inertia ontroller, Amplifiers, Dynam ers	facturing Process, The 8 hours ic Accuracy, Damping 8 hours ce Sensors.
Representatives of t Concepts and Lay Kinematic Layout, H UNIT-II Electromagnetic Dri Kinematics and Co of Harmful Vibratio UNIT-III Linear and Angular	he Robot Family, Relationship between the Level of Robot "Intelligence" ar vouts : Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping Dynamic Analysis of Drives ive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Vontrol of Automatic Machines: Position Function, Camshafts, Master Coons, Automatic Vibration Damping, Electrically Controlled Vibration Damp Feedback Sensors Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temp	nd the Product. ess, Productivity of a Manuf Variable Moment of Inertia ontroller, Amplifiers, Dynam ers	facturing Process, The 8 hours ic Accuracy, Damping 8 hours ce Sensors. on
Representatives of t Concepts and Lay Kinematic Layout, H UNIT-II Electromagnetic Dri Kinematics and Co of Harmful Vibratio UNIT-III Linear and Angular Transporting Devia UNIT-IV Introduction, Feedia	he Robot Family, Relationship between the Level of Robot "Intelligence" at routs: Processing Layout, Concept of an Automatic Manufacturing Proce Rapid Prototyping Dynamic Analysis of Drives ive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a V ontrol of Automatic Machines: Position Function, Camshafts, Master Co ons, Automatic Vibration Damping, Electrically Controlled Vibration Damp Feedback Sensors Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temp ces: General Considerations, Linear Transportation, Rotational Transportati Feeding and Orientation Devices ng of Liquid and Granular Materials, Feeding of Strips, Rods, Wires, Rithom Bins, General Discussion of Orientation of Parts, Passive Orientation, A	nd the Product. ess, Productivity of a Manuf Variable Moment of Inertia ontroller, Amplifiers, Dynam ers erature Sensors, Item Presen- ion, Vibrational Transportation	facturing Process, The 8 hours ic Accuracy, Damping 8 hours ce Sensors. on 8 hours Parts from Magazines,

	utomatic Assembling, Special Means of Assembly, Inspection Systems, Miscellaneous Mechanisms amics of Manipulators, Grippers & Guides.	
Course Outcomes: A	After completion of this course students will be able to	
CO 1	Explain industrial robots and their operational workspace characteristics & Manipulators.	K1, K2
CO 2	Analyze drives & its control.	K2
CO 3	Describe the use of sensors & solve kinematics of robot manipulators.	K3
CO 4	Apply feed material & orientation.	K4, K5
CO 5	Create application based prototypes of robots.	K1, K3
 Pessen, D. W Reference Books 3. Schey, John A 	ndler: Robotics designing the mechanisms for automated machinery, Prentice-Hall .: Industrial Automation, John Wiley & Sons, New York A., Introduction to Manufacturing Processes: Second Edition, McGraw-Hill International rthur J., Introduction to Robotics, Macmillan Publishing Company, New York, Collier Macmillan Pub	lishers, Londo
NPTEL/ Youtube/ 1		
Unit 1	https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1F	FkgPhpH&index=2
Unit 2	https://www.youtube.com/watch?v=XOg1KT6xD04&list=PLyqSpQzTE6M_XM9cvjLL0_Az	t1FkgPhpH&index=4
Unit 3	https://youtu.be/ksOgvhYdqX8	
Unit 4	https://youtu.be/Gc4BiUGiV-Q	
Unit 5	https://youtu.be/pSEjWxqE3R0	

	Bachelor of Technology Third Yea	r	
CourseCode	AEC0616	L TP	Credits
CourseTitle	ArtificialIntelligence	300	3
Course Objectives	: Student will learn about		
1	Historical perspective of Alandits foundations.		
2	Principles of AI toward problem solving and drawing inference thereof.		
3	Perception, knowledge representation, and different learning technique	5.	
4	Architecture of knowledge-Based System, Rule-based systems, and oth	er expert systems.	
5	Evolutionary computational algorithms and different search algorithms		
Pre-requisites: Ba	sicknowledgeofAIandMachine LearningConcepts.		
	CourseContents/ Syllabus		
UNIT-I	Introduction		8 Hours
Introduction to Art			signing a Learning
Introduction to Art System, Basics of	Introduction tificial Intelligence, Historical developments of Artificial Intelligence, w		signing a Learning
Introduction to Art System, Basics of exampledomains. UNIT-II Searching for solut adversarial Search	Introduction tificial Intelligence, Historical developments of Artificial Intelligence, w problem-solving: problem representation paradigms, statespace, satisfia	bilityvs optimality, pattern class ies: Local searchalgorithms and o chtechniques, HillClimbing,Best-	signing a Learning ification problems, 8 Hours ptimistic problems,
Introduction to Art System, Basics of exampledomains. UNIT-II Searching for solut adversarial Search	Introduction tificial Intelligence, Historical developments of Artificial Intelligence, we problem-solving: problem representation paradigms, statespace, satisfia SearchTechniques ions, Uninformed Search Strategies: DFS, BFS, Informed Search Strateg , Search for games, minimax, Alpha - Beta pruning, Heuristic Search	bilityvs optimality, pattern class ies: Local searchalgorithms and o chtechniques, HillClimbing,Best-	signing a Learning ification problems, 8 Hours ptimistic problems,
Introduction to Art System, Basics of exampledomains. UNIT-II Searching for solut adversarial Search reduction, Constrai UNIT-III IntroductionofLogi Resolution in FOF Cannibals Problem	Introduction tificial Intelligence, Historical developments of Artificial Intelligence, we problem-solving: problem representation paradigms, statespace, satisfia SearchTechniques ions, Uninformed Search Strategies: DFS, BFS, Informed Search Strateg , Search for games, minimax, Alpha - Beta pruning, Heuristic Sear ntsatisfaction, MeansEnds Analysis, IterativedeepeningHeuristicSearchand	bilityvs optimality, pattern class ies: Local searchalgorithms and o chtechniques, HillClimbing,Best- A*. ropositionallogic, FOPL, Semar ne AI problems: Water Jug Prob Problem. Knowledge representati	signing a Learning sification problems, B Hours optimistic problems, firstsearch,Problem B Hours S Hours optimistic Tableaux and optem, Missionaries-

UNIT-V	PlanningandUncertainty	8 Hours
Planningwithstates	paceSearch,ConditionalPlanning,Continuousplanning,Multi-AgentPlanning,Formsof learning, indu	uctive learning
	arning, learning decision trees, Neural Net learning andGeneticlearning.ProbabilisticMethods, Bayesia	
	esNetwork. Evolutionary computation: Swarm Intelligence, ant colony optimization Agents, Intelligent	
Intelligent Agents,	Virtual Agents, Multi-agent systems.	-
CaseStudy: Healtl	nCare,ECommerce,SmartCities.	
	: After completion of this course, students will be able to	
	historicalperspectiveofAlanditsfoundations.	K1
	nciplesofAI toward problem solving and drawing inference thereof.	K1, K4
	perception, knowledge representation, and different learning techniques.	K2, K3
	t architecture of knowledge-Based System, Rule-based systems, and other expert systems.	K3, K5
	lutionary computational algorithms and different search algorithms.	K4, K5
Textbooks:		
1. StuartRussel	l,PeterNorvig,"ArtificialIntelligence–AModernApproach",PearsonEducation. FourthEdition2021	
2. ElaineRicha	ndKevinKnight, "ArtificialIntelligence", McGraw-Hill3 rd Edition2010.	
ReferenceBooks:		
1. PatrickHenr	Winston, "ArtificialIntelligence", PearsonEducationInc., Thirdedition.	
		enceCoding,aProjec
	withPracticalExercises(7DaysCrashCourse,Book2)2020.	enee coung,ur rojee
	n, "ArtificialIntelligence- ANewSynthesis", HarcourtAsiaPvt. Ltd.	
3. NilsJ.Nilsso		
4. Alin the Wile	d:Sustainabilityin theAge of ArtificialIntelligence2020.	
 AIin theWile Knowledge- 	d:Sustainabilityin theAge of ArtificialIntelligence2020. BasedSystemsTechniquesandApplications(4-VolumeSet).	
 AIin theWile Knowledge- 	d:Sustainabilityin theAge of ArtificialIntelligence2020.	
 AIin theWile Knowledge- 	d:Sustainabilityin theAge of ArtificialIntelligence2020. BasedSystemsTechniquesandApplications(4-VolumeSet).	
 AIin theWild Knowledge- NPTEL/ Youtube 	d:Sustainabilityin theAge of ArtificialIntelligence2020. BasedSystemsTechniquesandApplications(4-VolumeSet). / Faculty Video Link:	

Unit3	https://nptel.ac.in/courses/106/106/106106202/
Unit4	https://nptel.ac.in/courses/106/106/106106213/
Unit5	https://nptel.ac.in/courses/106/105/106105152/

	Bachelor of Tech	nology T	'hi	rd Year	
Course Code	AEC0651	LT		Р	Credit
Course Title	Digital Signal Processing Lab	0 0		2	1
Course Objecti	ves: The student will learn about				
1	Various matrix operations, different types of signals an	d its prop	er	ties used in signal processing.	
2	The linear filtering using linear &circular convolution.				
3	The concept of frequency domain analysis of discrete t	me syste	m	using N point DFT & FFT.	
4	Performance of FIR and IIR filters using window techn				
5	Analysis of decimation and interpolation process for m	ulti-rate s	ig	nal processing.	
		List of E	кр	eriments	
Sr. No.		of Experi			CO
1	Write a MATLAB program to perform the various	matrix o	pe	rations: addition, subtraction, multiplication, and	CO1
	inverse of the given sequences as $a = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$	$\binom{2}{5}$			
2	To generate the different type of signals such as unit in both continuous and discrete time signal using MATLA		nit	step, ramp, exponential, sinusoidal and cosine for	CO1
3	Write a MATLAB program to perform amplitude-sca		e_(scaling and time shifting on a given signal $x(n)$ -	CO1
U	u(2n-3).	iiiig, tiii	0.	seame and time sinting on a given signal $x(n)$ -	001
4	Evaluate the DFT and IDFT of a given sequences $x(n)$	= {0,1,2,3	3}	and draw the magnitude and phase response of the	CO3
~	output sequence using MATLAB.				GO2
5	Evaluate and verify the linear convolution of the given for linear filtering applications.	sequence	es	$x(n) = \{0,1,0,1\} \& h(n) = \{2,3,4\} using MATLAB$	CO2
6	Evaluate and verify the circular convolution of the MATLAB for linear filtering applications.	given sec	ue	ences $x(n) = \{1,1,1,1\}$ & $h(n) = \{0,1,0,1\}$ using	CO2
7	Analysis of DIT-FFT algorithm for a given sequence x of given signals.	$(n) = \{n + $	1}	for $n=0, 1, 2, 3$ and draw the frequency spectrum	CO3
8	Design and analysis of a 2 nd order analog Low Pass But the pole-zero diagram, magnitude and phase response u				CO4
9	Design and analysis of a digital Low Pass and High Pa for M=7.				CO4
10	Design and analysis of decimation and interpolation factor D=4 and interpolation factor I=3.	of a give	ns	sequence $x(n) = \{1, 2, 2, 3, 2, 1\}$ for decimation	CO5
Course Outcon	nes: After completion of this course students will be a	ble to			
CO 1	Perform various matrix operations, different types of si	gnals and	it	s properties used in signal processing	K1, K2
CO 2	Perform the linear filtering using linear & circular conv				K1, K2
CO 3	Perform frequency domain analysis of discrete time sys		g Ì	N point DFT & FFT.	K1, K2, K3

CO 4	Design and evaluate the performance of FIR and IIR filters using window techniques and Butterworth approximation	K1,	K2,
	respectively	K3	
CO5	Design and analyse decimation and interpolation process for multi-rate signal processing.	K1,	K2,
		K3	

	Bachelor of Technology Thi	rd Year	
Course Code	AEC0614P	LTP	Credit
Course Title	Advanced IoT and Mobile Applications Lab	002	1
Course (Objectives: Student will learn about		
1	The basic fundamentals of Mobile Application Development.		
2	The various programs of UI fundamentals, layout and applications		
3	The implementation of multimedia and animation and connection	of notification and services.	
4	The real time applications.		
	Suggested List of Experim	nents	
Sr. No.	Name of Experiment		СО
1.	Implementing fundamentals of Mobile Application Development		CO1
	a. Case study on the architecture of personal smart phone,		
	b. Install the Android Studio 4.2 or higher for Android SDK 11		
	c. Install developer tools and build a test project to confirm t configured.	hat those tools are properly installed and	
2.	Implementing UI fundamentals and layouts and develop a program followings: -	n for student's records, Implement	CO1
	a. Use UI Widgets: 2 TextViews, 2 EditTexts, and one Push I	Buttons,	
	b. One Image button, One toggle button and One table 3x3,		
	Use linear layout, Absolute layout and Relative layout.		
3.	Implementing UI fundamentals and applications. Develop a progr followings: -	am to get students information, Implement	CO2
	a. To implement checkbox (minimum three options, Ask hob	bies)	
	b. Radio button for gender (Male, Female)		
	c. Radio group (minimum three options, Ask skills)		
	d. Progress bar. (Ask Course coverage)		
	e. Use Scroll and list view for checkbox		
	f. Use Image and grid view for radio group.g. Use date and time picker.		
4.	Implementing multimedia and animation.		CO2
••	1 0	sage using Plustooth	
	a. Interfacing Bluetooth connectivity and transmit and receive mes	sage using Diuetootii.	

	b. Develop program to show human walking animation.	
5.	Connecting Notifications and services	CO3
	a. Develop a program to send and receive SMS.	
	b. Develop a program to send and receive email.	
6.	Develop real-time applications with Android Studio	CO3
	a) Create a native calculator application.	
	b) Develop an application that makes use of database.	
	c) Develop a native application that uses GPS location information.	
	d) Sending sensor data from IoT enabled smart device and publishing on mobile application.	
Course	Outcomes: After successful completion of the course students will able to	
CO 1	Understand configuration of Android environment and development tools.	K2
CO 2	Develop rich user interfaces by using layouts, controls, user interface components and animations.	K6
CO 3	Construct android applications using data bases and connect services.	K6
CO 4	Implement, test and publish real time Android Applications.	K3

	Bachelor of Technology Thir	d Year	
Course Code	AEC0615P	LTP	Credit
Course Title	Robotics Lab	002	1
Course Obj	ectives: Student will learn about		
CO 1	The basic features of KUKA sim pro software.		
CO 2	The various programs on KUKA Sim Pro software.		
CO 3	Basics of the KUKA KR10 robotics arm.		
CO 4	Programming & Simulation of different task on KUKA KR10 rob		
	Suggested List of Experim	ents	
Sr. No.	Name of Experiment		CO
1.	Study of KUKA sim pro software and its features		CO1
2.	To write a simulation program for welding task.		CO1
3.	To write a simulation program for pick & place task on KUKA sir	n pro software.	CO2
4.	Simulation of finger gripper in KUKA sim pro with the help of a "r	nove tower" project.	CO2
5.	Sensing strategy and robot path creation for interrupted welding li	nes at car underbody.	CO3
6.	To study about robotics arm KR 10 and its features.	ž	CO3
7.	To verify the simulation program for task of pick & place on robot	tic arm KR-10.	CO4
8.	To verify the simulation program for welding task on robotic arm	KR-10.	CO4
Course Ou	tcomes: After successful completion of the course students will ab		•
CO 1	Understand the basic features of KUKA sim pro software		K2
CO 2	Understand and simulate the various programs on KUKA Sim Pro	software.	K2, K5
CO 3	Learn about the KUKA KR10 robotics arm.		K1, K2
CO 4	Simulate various programs on KUKA KR10 robotics arm.		K5

~ ~ .	Bachelor of Technology			
Course Code		LTP	Credit	
Course Title	AI & ML Lab	002	1	
Course Obje	ctives: Student will learn about			
6.	Implementation procedures for the machine learning algorith	ms.		
7.	Design MATLAB/Python programs for various Learning alg	orithms.		
8.	How to apply appropriate data sets to the Machine Learning	algorithms.		
9.	Identify and apply Machine Learning algorithms to solve rea	l world prot	lems.	
	List of Experime	nts		
Sr. No.	Name of Experime	nt		СО
1	Implement the S algorithm for finding the most specific hy data samples. Read the training data from a .csv file.	pothesis bas	ed on a given set of training	CO1
2	For a given set of training data examples stored in a .c Candidate-Elimination algorithm to output a description of the training examples.			CO1
3	Build an Artificial Neural Network by implementing the Back propagation algorithm and test the same using appropriate data sets.		CO2	
4	Implement the non-parametric Locally Weighted Regression algorithm in order to fit data points. Select appropriate data set for your experiment and draw graphs.		CO2	
5	Write a program to implement the naïve Bayesian classifier for a sample training data set stored as a .csv file. Compute the accuracy of the classifier, considering few test data sets.			CO2
6	Assuming a set of documents that need to be classified, us perform this task. Built-in Java classes/API can be used to v precision, and recall for your data set.			CO2
7	Write a program to construct a Bayesian network considered demonstrate the diagnosis of heart patients using standard Java/Python ML library classes/API.	l Heart Dis	ease Data Set. You can use	CO3
8	Apply EM algorithm to cluster a set of data stored in a .csv file. Use the same data set for clustering using k-Means algorithm. Compare the results of these two algorithms and comment on the quality of clustering. You can add Java/Python ML library classes/API in the program.			CO4
9	Write a program to implement k Nearest Neighbor algorithm to classify the iris data set. Print both			CO4
10	Write a program to demonstrate the working of the deca appropriate data set for building the decision tree and apply	sion tree ba	ased ID3 algorithm. Use an	CO4
Course Outo	omes: After successful completion of this course, students w			Blooms Leve

CO 1	Explain the implementation procedures for the machine learning algorithms.	K ₃
CO 2	Design Python programs for various Learning algorithms.	K ₃ , K ₄
CO 3	Apply appropriate data sets to the Machine Learning algorithms.	K ₃ , K ₄
CO 4	Identify and apply Machine Learning algorithms to solve real world problems.	K ₅

	B. TECH. THIRD YEAR		
Course code	ANC0601	L T P	Credits
Course Title	CONSTITUTION OF INDIA, LAW AND ENGINEERING	2 0 0	2
•	tive: To acquaint the students with legacies of constitutional development in India and help them of India and philosophy behind it.	to understand	l the most diversified
Pre-requisites	Computer Organization and Architecture		
	Course Contents / Syllabus		
UNIT-I	INTRODUCTION AND BASIC INFORMATION ABOUT INDIAN CONSTITUTION		8 Hours
Fundamental Ri Amendment of	ence Act of 1947,Enforcement of the Constitution, Indian Constitution and its Salient Features, 7 ghts, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal the Constitutional Powers and Procedure, The historical perspectives of the constitutional ar- onal Emergency, President Rule, Financial Emergency, and Local Self Government – Constitution	l System, Ce mendments i	ntre-State Relations, n India, Emergency
UNIT-II	UNION EXECUTIVE AND STATE EXECUTIVE		8 Hours
Indian President Independence of The Lokpal and	A Parliament Functions of Rajya Sabha, Functions of Lok Sabha, Powers and Functions of the Pre- with the United States, Powers and Functions of Vice-President, Powers and Functions of the the Supreme Court, Appointment of Judges, Judicial Review, Public Interest Litigation, Judicia Lok ayuktas Act 2013, State Executives – Powers and Functions of the Governor, Powers and te Cabinet, Functions of State Legislature, Functions of High Court and Subordinate Courts.	Prime Mini al Activism, I	ster, Judiciary – The LokPal, Lok Ayukta,
UNIT-III	INTRODUCTION AND BASIC INFORMATION ABOUT LEGAL SYSTEM		8 Hours
law, Principles t District Consum	m: Sources of Law and the Court Structure: Enacted law -Acts of Parliament are of primary legates aken from decisions of judges constitute binding legal rules. The Court System in India and F er Forum, Tribunals, High Courts, Supreme Court). Arbitration: As an alternative to resolving n dispute can agree that this will instead be referred to arbitration. Contract law, Tort, Law at work INTELLECTUAL PROPERTY LAWS AND REGULATION TO INFORMATION	oreign Court g disputes in	iers (District Court,
			0 110015

Intellectual Property Laws: Introduction, Legal Aspects of Patents, Filing of Patent Applications, Rights from Patents, Infringement of Patents, Copyright and its Ownership, Infringement of Copyright, Civil Remedies for Infringement, Regulation to Information, Introduction, Right to Information Act, 2005, Information Technology Act, 2000, Electronic Governance, Secure Electronic Records and Digital Signatures, Digital Signature Certificates, Cyber Regulations Appellate Tribunal, Offences, Limitations of the Information Technology Act.

UNIT-V	BUSINESS ORGANIZATIONS AND E-GOVERNANCE	8 Hours
Association, Governance, and Secessio	, Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of As Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up. E-Governance and row Need for reformed engineering serving at the Union and State level, Role of I.T. professionals in Judiciary, P nism in few states creating hurdles in Industrial development.	ole of engineers in E-
COURSE O	UTCOMES: After completion of this course students will be able to	
CO 1	Identify and explore the basic features and modalities about Indian constitution.	K1
CO 2	Differentiate and relate the functioning of Indian parliamentary system at the center and state level.	K2
CO 3	Differentiate different aspects of Indian Legal System and its related bodies.	K4
CO 4	Discover and apply different laws and regulations related to engineering practices.	K4
CO 5	Correlate role of engineers with different organizations and governance models	K4
Text Book	s:	
1. M La	xmikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill	
2. Brij F	Kishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.	
3. Gran	ville Austin: The Indian Constitution: Cornerstone of a Nation (Classic Reissue), Oxford University Press.	
Reference	Books:	
1. Madh	av Khosla: The Indian Constitution, Oxford University Press.	
2. PM B	Bakshi: The Constitution of India, Latest Edition, Universal Law Publishing.	
3. V.K.	Ahuja: Law Relating to Intellectual Property Rights (2007)	

Course Code	Bachelor of Technology Third Year ANC0602	LTP	Credits
Course Title	Essence of Indian Traditional Knowledge	200	NC
Course Objectives	s: In this course, the student will:		
1	Learn the basics of past Indian politics and state polity.		K ₁ , K ₂
2	Aware of the Vedic system		K ₁
3	Understand the different religions and religious movements in India.		K2
4	Learn the basic knowledge about the ancient history of Indian agriculture, science & tec ayurveda	chnology, and	K1
5	Understand Indian dances, fairs & festivals, and cinema.		K ₂
Pre-requisites: Po	litical science		·
	Course Contents / Syllabus		
UNIT-I	Society State and Polity in India		4 hours
Kingship, Council State, Society in	ndia: Evolutionary Theory, Force Theory, Mystical Theory Contract Theory, Stages of State of Ministers Administration Political Ideals in Ancient India, Conditions of the Welfare of Socie Ancient India, Purusārtha, Āshrama or the Stages of Life, Marriage, Understanding Gende Vomen in Historical traditions, Challenges faced by Women.	eties, The Sev	en Limbs of th
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Intangible Culture l	Heritage, Calendars, Current developments in Arts and Cultural, Indian's Cultural Contribution to the World, In	ndian Cinem
Course outcome: A	After completion of this course students will be able to	
CO 1	Understand the basics of past Indian politics and state polity.	K2
CO 2	Understand the Vedas, Upanishads, languages & literature of Indian society.	K2
CO 3	Know the different religions and religious movements in India.	K4
CO 4	Identify and explore the basic knowledge about the ancient history of Indian agriculture, science & technology, and ayurveda.	K4
CO 5	Identify Indian dances, fairs & festivals, and cinema.	K1
Text books		<u> </u>
4. S. Baliyan,	Indian Art and Culture, Oxford University Press, India	
5. Nitin Singh	ania, Indian Art and Culture: for civil services and other competitive Examinations,3rd Edition, Mc Graw Hill	
6. Swami Jitat	manand, Modern Physics and Vedant, Bharatiya Vidya Bhavan	
Reference Books		
4. Romila Tha	par, Readings In Early Indian History Oxford University Press, India	
5. Basham, A.	L., The Wonder that was India (34th impression), New Delhi, Rupa & co	
6. Sharma, R.S	S., Aspects of Political Ideas and Institutions in Ancient India (fourth edition), Delhi, Motilal Banarsidass	